

# Data Acquisition System of the Virgo Gravitational Waves Interferometric Detector

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**Abstract**—Virgo is an experiment aiming at the detection of gravitational waves emitted by astrophysical sources. Its detector, based on a 3 km arms interferometer, is a complex setup which requires several digital control loops running up to 10 kHz, an accurate and reliable central timing system and an efficient data acquisition, all of them being distributed over 3 km. We overview here the main hardware and software components developed for the data acquisition system (DAQ) and its current architecture. Then, we briefly discuss its connections with interferometer's controls, especially through the automation of the interferometer's startup procedure. Then, we describe the tools used to monitor the DAQ and the performances we measured with them. Finally, are described also the tools developed for the online detector monitoring, mandatory complement of the DAQ for the commissioning of the Virgo detector.

**Index Terms**—Data acquisition (DAQ), data display, gravitational waves, interferometer, online monitoring, Virgo.

## I. INTRODUCTION

THE Virgo experiment [1], [2] aims at the detection of gravitational waves of astrophysical origin by using a suspended Michelson interferometer with 3 km arms length. The commissioning of this interferometric detector reaches currently its end and the sensitivity of the apparatus is approaching the aim requested for a possible gravitational wave detection, in a bandwidth spanning from a few Hertz to several kilohertz. As shown in Fig. 1, Virgo detector is a Michelson interferometer using a 20 W Nd:YAG laser stabilized in power and frequency and an injection system that includes an input mode-cleaner (a 3 mirrors cavity maintained resonant on the laser TEM<sub>00</sub> mode). The

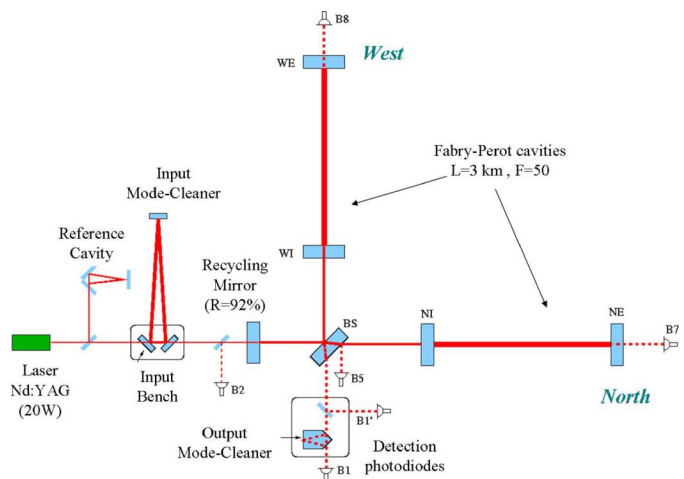


Fig. 1. Optical configuration of the Virgo interferometer.

detection system includes a set of detection photodiodes and an output mode-cleaner that improves the dark fringe contrast. The main improvements with respect to a simple Michelson are 3 km long Fabry–Perot cavities in each arm that increase up to 100 km the optical arms length and a recycling mirror that increases the light power inside the interferometer. Once the interferometer is set on its working point (optical cavities resonant and interference kept on the dark fringe), the arms length modification due to a gravitational wave is detected by apparition of light at the interferometer's output.

To reduce as much as possible the environmental noises that could affect the dark fringe signal, the main components of the interferometer are placed under vacuum and the mirrors are suspended under sophisticated anti-seismic suspensions that reduce the horizontal seismic motion by a factor  $10^{14}$  above 10 Hz [3], [4]. The input and output mode-cleaner needs to be seismically isolated and are thus also suspended.

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Such a long base-line interferometer needs a data acquisition system [5], [6] able to collect in a coherent way all the data needed for the signal extraction and the qualification of the detector. This requires a site wide timing system and several dedicated readouts interfaced with the control loops distributed over the site. It requires also tools to format, transport and write the data. Also mandatory are online monitoring tools to display and analyze in real time the state of the detector.

In detection configuration, the Virgo interferometer requires many control loops, that need to be developed and tuned [7], [8]. Since most of those controls are digital, the data acquisition (DAQ) has strong connections with them: on one hand, the timing system of the DAQ is the same as the one used to drive the controls, on the other hand, the digitized control loop signals are often collected synchronously by the DAQ. This put an additional strong constraint on the DAQ: to not disturb the digital controls. Given the complexity of the interferometer, the control systems have continuously evolved during the commissioning phase, with an increasing number of controls being turned on and a continuous noise hunting leading to a regular improvement of the detector sensitivity. This puts also flexibility and scalability constraints on the data acquisition. Finally, the DAQ has to challenge a strong request of reliability because the detector should be operated 24 hours per day, all year long.

We first overview, in Section II, the standard and custom components of the DAQ chosen under those constraints. Then, Section III describes the current architecture of the data acquisition, including online data access and online data processing set up with the DAQ software tools. Section IV is a short description of the two control setups which has strong connections with DAQ: the interferometer's control loops and the automation of the interferometer's locking procedure. Then, Section V focuses on the DAQ monitoring and on the DAQ performances measured. Finally, Section VI deals with the main software tools developed for the online detector monitoring which is a mandatory complement of data acquisition.

## II. STANDARD AND CUSTOM DAQ COMPONENTS

The choices made for the hardware and software components of the data acquisition have been guided by the constraints previously described and by the easiness of use and maintenance. Thus, whenever possible, standard solutions have been adopted for each DAQ hardware component. Moreover, based on those standard choices, a tool mandatory for the control of the interferometer and for the data acquisition has been developed: the timing system. Finally, a set of home-made libraries has been developed to provide plug-and-play DAQ software tools.

### A. Standard Components

For the front-end part, we use data transmission through optical links to reduce propagation delays over 3 km and to reduce the electromagnetic noise. We use also VME numerical electronic boards associated with RIO8062 PowerPC CPU under LynxOS [9] to handle the real time of Virgo control loops and front-end data acquisition. In addition, home-made VME boards

have been developed for the timing system [10], for the reception and transmission through optical links [11], for the suspensions control (DSP) [12] and for the CCD cameras readout used in local controls and beam shape measurements [13].

For data collection and online processing, we use workstations under Linux SL4, shared memories and Gigabit Ethernet with TCP/IP protocol to exchange the data between the processes. In addition, a set of home-made C libraries has been developed to more easily propagate the large data flow of Virgo between DAQ processes. The choice of the C language was done in 1997 to use a well established standard.

### B. The Virgo Timing System

Control loops and data acquisition of a 3 km arms interferometer need to be synchronized over a large length scale. In addition, to guarantee a data analysis in coincidence with other interferometric detectors like LIGO [14], it is necessary to stamp the data with a common time reference.

To fulfill this requirement, a GPS based central timing system has been developed to synchronize the Virgo interferometer's controls and readouts. This timing system provides to the Virgo experiment a 1 PPS signal with a jitter less than 1  $\mu$ s. In addition, delays of optical links between the buildings have been measured and accounted for [10]. Finally, a cross-check of the GPS reference 1 PPS signal is done with a local Rubidium atomic clock [15]. and measurements have been done, within a Virgo-LIGO collaboration, to check the inter-experiment timing accuracy [16]. Details about the timing system can be found in [6].

### C. The DAQ Libraries

The home-made libraries developed for timing and readout management have been described in [6]. Particular emphasis is given here to the home-made libraries developed for the data collection.

Once the data have been digitized and acquired synchronously thanks to front-end readouts paced by the timing system, they need to be formatted to be propagated on the Ethernet network and stored on disk. A data format for gravitational wave detectors has been developed since 1996 in the framework of a Virgo-LIGO collaboration [17]: the "frame" format. It has been adopted now by several other gravitational waves detectors all over the world. Two libraries, "Fr" and "Frv" [18], have been developed to manage the frame format and the vectors of data. All the DAQ and online processing make an extensive use of those two libraries. In addition, a Frame Distribution library "Fd" [19] has been developed to manage the input/output of the frame-formatted data. It is based on the use of a custom library "FdShm" [20] that manages frames in shared memory and on the use of the "Cm" library [21] that encapsulates the TCP/IP Ethernet protocol. We have also created "FdIOServer," an elementary part of the DAQ shown in Fig. 2, that exchanges frames through Ethernet or shared memory. Thanks to the "Fd" library, "FdIOServer" can easily embed any requested online processing algorithm. In addition, "Cfg," a general purpose library, has been developed, mainly to handle the parsing of configuration files and the exchange

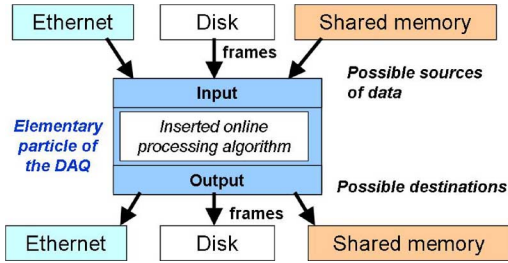


Fig. 2. Basic element of the data acquisition, created thanks to the “Fd” library. In this element can be introduced any online processing software developed in Virgo like for instance a resampling algorithm, a detector monitoring algorithm or an automation algorithm.

of informations with the graphical interface that controls and monitors the DAQ processes.

### III. DATA ACQUISITION ARCHITECTURE

As shown in Fig. 3, the Virgo data acquisition architecture can be split into three levels: the “front-end readouts,” the “frame builders” and the “frame collectors.” Those three levels have been mainly described in [6].

- *First level:* The front-end readouts run on RIO8062 CPU. They are synchronized by the timing system and produce all the raw data acquired in Virgo. Some of them are also involved in the control loops and need to be reliable and fast enough. As a consequence, those processes do not build frames but send their data through optical links down to frame builders.
- *Second level:* The frame builders are a key feature of the data collection. They collect data from the various front-end readouts and put them under frame format. Two specific softwares have been developed in Virgo to this purpose: the “slow frame builder,” that collects the slow monitoring data (sampling frequency  $\leq 1$  Hz), and the, “fast frame builder,” that collects all the fast channels from the front-end readouts. The fast frame builder run on RIO8062 CPU and uses a custom data compression algorithm to reduce by about 2.5 the size of the frames sent through Ethernet down to the frames collectors.
- *Third level:* The frame collectors, historically called, “main frame builders,” run on Linux workstations. They collect asynchronously the frames sent by several frames builders and merge them using the frame number. The result of the merging is a frame written in a shared memory [20] and immediately available online for next steps of the DAQ chain or online data access purposes.

As can be seen in Fig. 4, the main modifications with respect to the architecture described in [6] is that the raw data collected are used for the automation of the interferometer’s locking procedure and also sent to several online processing tasks. In a last step, the results of the online processing are merged with the main data stream through a last frame collector (FbmSt) which sends the resulting frames down to data storage.

#### A. Data Streams and Data Access

Within this architecture, several data streams are produced. The main Virgo data stream is made of all the raw data collected

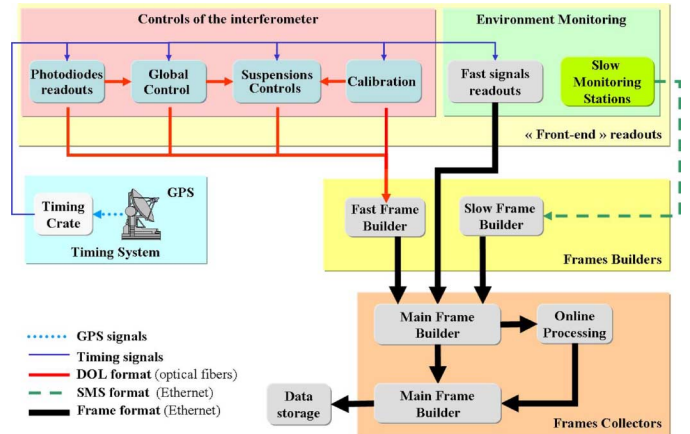


Fig. 3. General architecture of the Virgo data acquisition, with the 3 levels, “front-end,” “frame builders” and “frame-end.” Also shown is the GPS based timing system that rhythms the front-end readouts and the various data format used.

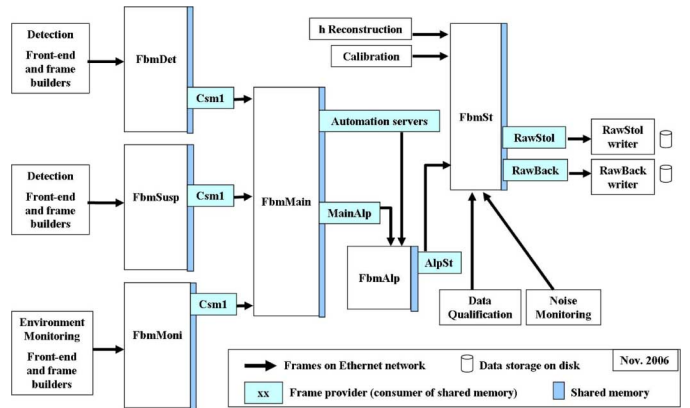


Fig. 4. Configuration of the data acquisition system in November 2006. Boxes at left aim at describing all the processes of the “front-end” and “frame builders” levels, that means about 110 processes distributed over 85 CPUs and DSPs. The data are collected by three upstream “frames collectors” FbmMoni, FbmSusp and FbmDet and passed to the automation system (FbmMain, Automation servers, FbmAlp). A last frames collector, FbmSt, adds to the main stream the data provided by the calibration system and by some of the online processing tasks (h Reconstruction, detector monitoring and noise monitoring). Data storage (RawStol) is secured by a short time scale parallel storage (RawBack).

through the three levels previously described. It represents today a total of about 2340 channels acquired (1370 fast channels and 970 slow monitoring channels), for a total data rate of about 20 MB/s (8 MB/s after data compression), which means about 690 GBytes per day written on disk [22].

Mainly, two other data streams are produced by some of the online processing tasks implemented: the 50 Hz resampling of the data and the trend data computation. As shown in Fig. 5, the 50 Hz resampling (Fbt50Moni, Fbt50Susp, Fbt50Det) is distributed over the three upstream frames collector and provides resampled data (after anti-aliasing filter of 7th order) to a dedicated frames collector Fbm50 where they are written on disk. This allows a fast access to several weeks of data in order to follow and study the low frequency behavior of the interferometer. The trend data are statistics (mean, rms, max, min) computed for each channel by a dedicated process (FbtMain in Fig. 5) and written on disk along with the slow monitoring data.

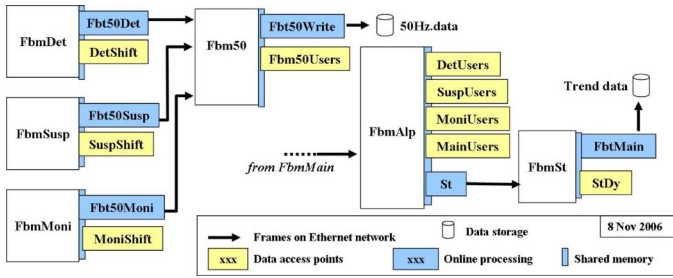


Fig. 5. Online processing tasks (blue color) and online data access points (yellow color) within the DAQ architecture, in November 2006.

The trend data stream allows to monitor over several months the evolution of the detector, of the controls, of the environment or of the DAQ itself.

The access to those various data streams can be done online thanks to access points (or frames providers) connected to the shared memory of one of the frames collectors. Those access points (see Fig. 5) are based on the FdIOServer described in Section II-C. They have no link with the DAQ except the shared memory where they read the data. They consume at most some percents of CPU and allow to connect online, through Ethernet, any tool developed in Virgo for the visualization, monitoring or writing of the data.

#### IV. DAQ USAGE IN INTERFEROMETER'S CONTROLS

##### A. DAQ and Interferometer's Digital Control Loops

the DAQ monitors all the signals involved in the control loops. In addition, several signals, including the dark fringe signal, are acquired by readouts used at the same time for the DAQ and for the controls of the interferometer. The main control loops readouts involved also in the DAQ are the following:

- *The longitudinal global control:* it uses photodiodes signals read at 10 kHz to compute the correction signals that drive the mirrors longitudinal position, thus the optical cavities length.
- *The alignment global control:* it uses quadrant photodiodes signals read at 500 Hz to determine the beams position and to compute the correction signals that drive the mirrors angular position.
- *Suspensions local control and inertial damping:* they use position sensing devices read at 500 Hz and camera signals read at 50 Hz to compute the correction signals that drive the suspension's position and orientation.
- *Laser frequency and input mode-cleaner length control:* it uses photodiodes signals read at 10 kHz to compute the correction signals that drive the input laser beam frequency and the input mode-cleaner cavity length.

##### B. DAQ and Interferometer's Lock Automation

To put the interferometer on its working point, a sequence of more than hundred monitoring and manual actions is required from operators in control room. It appeared rapidly that, using the signals monitored through the DAQ and using Ethernet messages, this interferometer's locking sequence could be

automated. In 2005, a software named "Alp" was developed in Virgo for this automation. Practically, a set of Alp processes gets data from the shared memory of a dedicated DAQ frames collector (FbmMain) and, by successive steps, controls the lock of the interferometer until its working point. Those steps are numbered from 1 to 12, among which the main ones are:

- *Step 1:* Mirrors are pre-aligned (except recycling mirror), Fabry-Perot cavities are locked and the interference is locked on "gray fringe."
- *Step 4:* Recycling mirror is aligned and recycling cavity is locked. Light power on the beam splitter goes up to several hundreds of watts.
- *Step 8:* The interference is locked on dark fringe and the global control of alignment is activated.
- *Step 10:* The output mode-cleaner is locked on the laser TEM00 mode and the dark fringe control uses photodiode B1 placed after the output mode-cleaner.
- *Step 12:* Tidal control is activated as well as the reallocation of controls on intermediate part of mirrors suspensions.

Then, a set of filters are applied to reduce the control noises, permanent calibration signals are injected on mirrors longitudinal controls and "Science Mode" flag is switched on.

Each step of this locking sequence is defined in the configuration of an Alp process, which contains a set of conditions on the signals provided by the DAQ and a set of actions to be done on the interferometer. Those actions are done through Ethernet by sending Cm messages [21] to the softwares that control the interferometer's sub-systems. Each step defined in the configuration can be conditioned by the result of the previous steps and the full sequence of controls can thus be done easily and quickly. The low latency of the DAQ (about 2 s between front-end data acquisition and commissioner's data visualization) allows the Alp automation software to have enough control speed and to complete the whole automated sequence in currently less than 15 min (see Fig. 6), if we exclude the step 8, which is currently down-limited to 20 min in order to overcome the thermalization of the mirrors heated by the laser beam.

#### V. DAQ MONITORING AND PERFORMANCES

As we will see in Section VI, the Virgo detector and its environment are permanently monitored, but this does not guarantee the availability and the validity of the data. At each level of the data acquisition chain (front-end, frame builders, frames collectors), a failure can be at the origin of missing or corrupted data. Thus, all the processes involved in the data acquisition or in the data storage are monitored.

Using the GUI tool Xforms [23], a graphical interface [24] has been developed to control and monitor each DAQ process. This interface allows to start and stop the processes and to change their configuration. In addition, it provides several informations like memory consumption, process id, TCP name, etc... and builds a web page showing the online status of the DAQ processes with a latency below 2 seconds. Fig. 7 shows



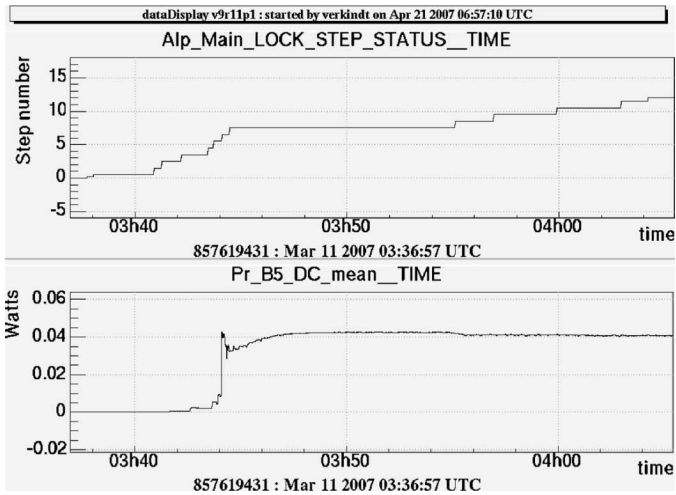


Fig. 6. A typical sequence of the automated interferometer startup procedure. Upper plot shows the evolution of the `Alp_Main_LOCK_STEP_STATUS` value that monitor the startup steps. Lower plot shows the light power on the beam splitter that increases a lot when the recycling cavity is locked ( $y$  axis indicates the power's fraction `Pr_B5_DC_mean` received by the photodiode).

Collect	active	(golden) GP5 860925740 - Apr 18, 2007 (108) 12:02:07
TServer	Golden	fr:00269 run05350 GP 5:860925740-2700 - Qc 0x0000e022
Detection DAQ line		
FbMain	Golden	fr:00268 (1.85e+03 KB) [0/4] - sTime 0.78s
FbMainP	Active	fr:00268 (1.14e+03 KB) [0/4] - lostGcAll - sTime 0.568s
FbMainE	Golden	fr:00268 (672 KB) [0/4] - sTime 0.291s
FbMainV	Golden	fr:00268 (972 KB) [0/4] - sTime 0.402s
FbMainDet	Active	fr:00269 (18.067 KB) GP 5:860925740 Latency: 0.0787 - lostGc_Locking_Mirror
FbMainDet	golden	fr:00268 (4.67 MB) latency:1.88 adc:495 sms:23

Fig. 7. Part of the graphical interface used to control and monitor the data collection DAQ processes. First column (colored buttons) and third column show the status of the process. Second column (with arrows) give access to the logfile of each process. Detailed information (frame number, rate, latency,...) is provided on the last column.

parts of the graphical interface used to monitor all the processes used in the data collection.

In addition, some slow monitoring data are created by the data acquisition itself. Those data allow to monitor for instance the correctness of the timing stamp, the efficiency of the data acquisition, the total number of channels acquired, the data rate along the DAQ chain, the latencies introduced in the data acquisition chain. Among those data, the most important ones are visualized by trend plots on the web [25].

Since January 2002, those monitoring tools have allowed to estimate the performances of the data acquisition system in terms of stability, efficiency, data rate and latency. The main results are the following:

- The mean DAQ latency has been reduced to less than 2 seconds at the level of `FbmMain`. This 2 seconds latency and the reliability of the DAQ has allowed to develop the automation of the interferometer's startup through the DAQ. Upper plot of Fig. 8 shows this latency, that goes to its maximal authorized value of 8 each time par of the DAQ chain does not send data to the `FbmMain` collector.

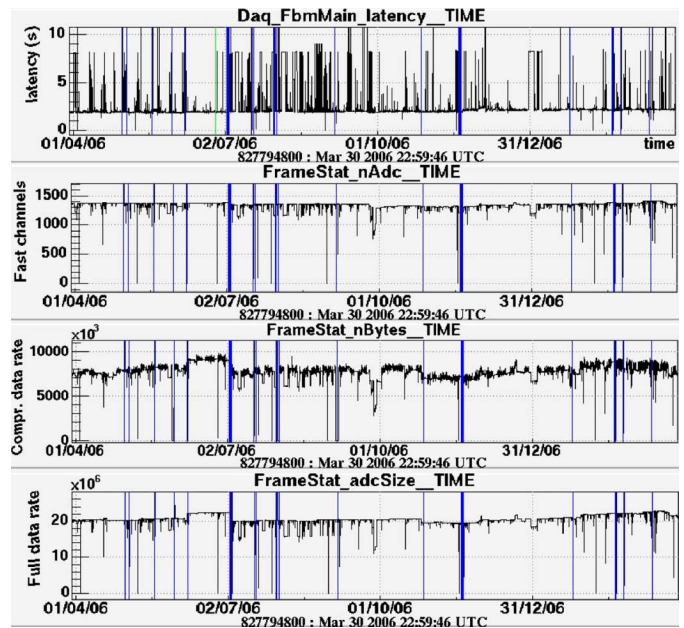


Fig. 8. From top to bottom: DAQ latency, number of fast channels and data rate (compressed and uncompressed) seen by DAQ between March 31st 2006 and March 31st 2007. Blue or green vertical lines indicates periods where data are missing.

- The data rate permanently sustained by the DAQ is about 20 MBytes/s (4 times larger than foreseen in the DAQ design), with more than 1350 fast channels (sampling frequency above 1 Hz) recorded.
- The percentage of data loss is difficult to estimate because the number of channels acquired fluctuates according to the commissioning needs. Nevertheless, it has been estimated on the dark fringe signal (main signal that will be used for gravitational waves search). It is less than 0.1% for each commissioning run and about 0.3% over the whole period from January 2004 to November 2006. This estimation takes into account all the periods of detector's maintenance, disks problems, network failure, upgrade of machines or operating system, stops of the DAQ (for architecture's modifications or for the use of new versions of the libraries).

The two lower plots of Fig. 8 show, over one year, the continuous increase of the data rate (compressed and uncompressed), while the two upper plots show the relative stability of the mean latency and the increase of the number of fast channels collected. Table I shows the evolution of some DAQ numbers since July 2002, where we can see the increase of readout processes, channels number and data rate, while the latency and data loss are reduced down to 2 seconds and 0.3% respectively. Table II shows the duty cycle of the data acquisition between January 2004 and September 2006 and over most of the commissioning runs. This performance is illustrated by Fig. 9, which shows the integrated DAQ duty cycle over one year.

The Virgo data acquisition system has run permanently since early 2001, with the good performances described above. It sustained an increasing number of channels reaching now more than 1350 "fast" signals. It corresponds to a raw data rate of

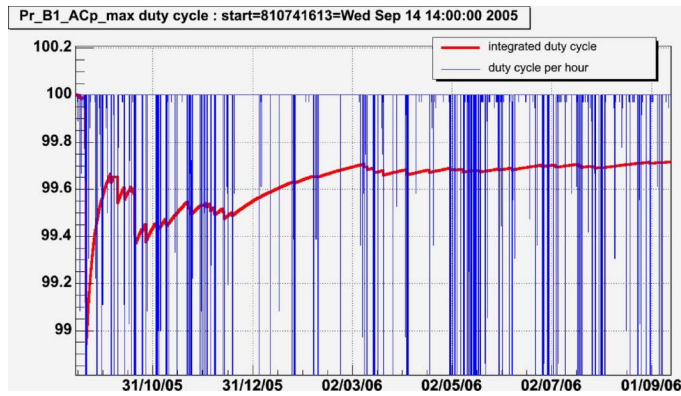


Fig. 9. DAQ duty cycle estimated by the presence of the dark fringe channel in the stored raw data, between Sept. 2005 and Sept. 2006.

TABLE I

EVOLUTION OF SOME DAQ PARAMETERS OVER THE LAST 4 YEARS. COMMENT: THE FULL LATENCY IS TAKEN BETWEEN FRONT-END READOUT AND DATA STORAGE (IN 2006, IT INCLUDED ABOUT 20 ADDITIONAL SECONDS DUE TO QUALIFICATION OF THE  $h$  RECONSTRUCTION PROCESS). THE ONLINE LATENCY IS TAKEN BETWEEN FRONT-END READOUT AND THE LAST FRAMES COLLECTOR (FBMMAIN) WHERE DATA ARE READ BY THE AUTOMATION PROCESSES. THE PERCENTAGE OF DATA LOST IS THE PERCENTAGE OF TIME WHERE THE DARK FRINGE SIGNAL WAS ABSENT

Date	Jul2002	Jul2003	Feb2004	Dec2004	Aug2005	Nov2006
Run (duration)	E4 (72h)	C0 (28h)	C2 (72h)	C5 (120h)	C6 (336h)	WSR5 (72h)
Fast raw data channels	690	790	1180	1340	1330	1385
Trend data channels	3260	4000	5670	7880	7450	9473
Compr. data rate (MB/s)	4.2	4.7	5.8	6.7	6.3	7.9
Front-end readouts	48	-	76	109	94	102
Frame builders	22	-	30	30	31	34
Frames collectors	4	4	5	7	8	11
Data storage (TB)	2	6	32	70	120	120
Full latency (s)	8	8	7	6	4	22.7
Online latency (s)	8	8	6	5	3	1.9
Data lost percentage	-	-	-	0.18%	0.24%	0.023%
Data streams	2	3	4	6	6	6

TABLE II

ESTIMATION OF THE DAQ DUTY CYCLE. COMMENT: ESTIMATION IS DONE BETWEEN JANUARY 2004 AND SEPTEMBER 2006 FOR THE TREND DATA STREAM AND THE RAW DATA STREAM (DARK FRINGE SIGNAL ONLY). ALSO SHOWN IS THE DAQ DUTY CYCLE FOR EACH COMMISSIONING RUN SINCE JANUARY 2004 .

Data stream	Epoch	Start GPS	duration	Duty cycle
Trend data	Jan2004-Jan2005	757585800	31400000	96.509%
Trend data	Sep2005-Sep2006	810741613	31400000	97.770%
Raw data	Jan2004-Jan2005	757585800	31400000	99.997%
Raw data	Sep2005-Sep2006	810741613	31400000	99.716%
Raw data	C5 (02 Dec 2004)	786031360	436000	99.828%
Raw data	C6 (28 Jul 2005)	806602213	1296000	99.760%
Raw data	C7 (14 Sep 2005)	810741613	403200	99.987%
Raw data	WSR1 (08 Sep 2006)	841784413	201600	100.000%
Raw data	WSR2 (23 Sep 2006)	843001214	201600	99.987%
Raw data	WSR5 (10 Nov 2006)	847231214	201600	99.977%
Raw data	WSR6 (01 Dec 2006)	849045614	201600	99.995%
Raw data	WSR7 (12 Jan 2007)	852678014	201600	99.940%
Raw data	WSR8 (9 Feb 2007)	855093614	201600	99.976%

20 MBytes/s currently provided to control room with a mean latency of 2 seconds.

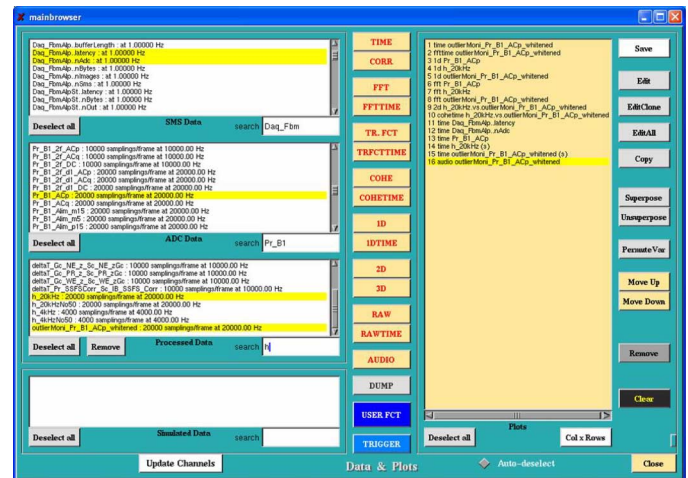


Fig. 10. Graphical panel that manages the signals and the plots of the dataDisplay. It allows to browse the channels available, to choose the type of plots to display, to manage the superposition of plots or to edit their parameters.

## VI. ONLINE DETECTOR MONITORING

Virgo must be operated 24 h per day while very exposed to instrumental and environmental noises because of its high sensitivity. This constraint requires a highly selective data analysis and a reliable data acquisition. But it requires also a permanent monitoring of the interferometer's running conditions, first to provide in control room a quickly updated information on the detector's behavior, then to help in the selection of data segments where data analysis can be done with confidence. Virgo has developed since several years some software tools for the online monitoring of the detector. Most of those tools are presented here. They use often the software libraries created for the DAQ and, thus, benefit from their reliability.

### A. The Data Display

A first mandatory need of the Virgo commissioning was to monitor online from the control room a large number of signals provided by the interferometer. To this purpose, a software tool dedicated to the visualization of the data has been developed for the Virgo experiment: the dataDisplay [26]. It allows, through a "buttons and browsers" graphical interface, to read, online or offline, the frame formatted data produced in Virgo. Fig. 10 shows one of the dataDisplay's graphical interface panels.

Over the last years, the dataDisplay has enriched with several functionalities and new types of plots. It is able to create and edit plots that could help for the monitoring of the detector (time plots, spectra, 1D or 2D distributions, beams imaging...) or the signals analysis (transfer function, coherence plot, spectrograms...). The dataDisplay can also do operations on the signals in order to monitor some combinations of signals used in the controls. It can superpose plots (including plots of data taken at different times), do operations on the plots, view the content of the frames or listen to the data. Fig. 11 shows an example of online data visualization, during the WSR1 run in September 2006.

The dataDisplay uses open source code: a graphical interface created with the Xforms library [23], a data distribution management based on the frame library [18], the Fd and Cm libraries,

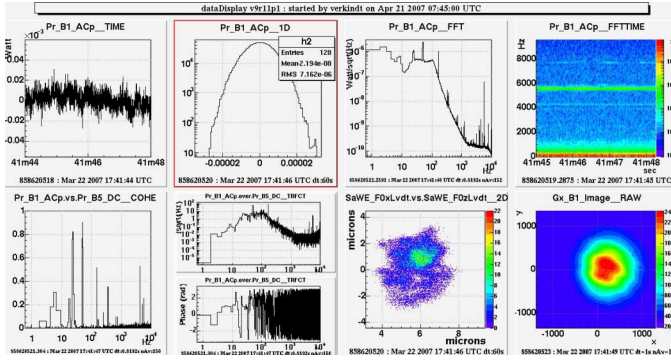


Fig. 11. Examples of plots created online by the dataDisplay with the data received from the DAQ. On first row are visible, from left to right, the dark fringe signal versus time, its distribution, its frequency spectrum and its time-frequency spectrogram. In the second row are shown the coherence and the transfer function (module and phase) between the dark fringe signal and the light power on beam splitter. Last two plots monitor the horizontal position of the upper part of west mirror suspension and the profile of the beam at the output of the interferometer.

and a plots visualization based on the ROOT libraries developed at CERN [27]. It has been compiled and used under OSF1 v5, Mac OSX, SunOS, Linux RedHat 7.2, Linux RedHat 9 or Scientific Linux 4.2.

The dataDisplay has been widely used in the Virgo control room to monitor online the detector. It has evolved over several years, according to the needs of the Virgo commissioning, and is still improving, concentrating now on the data analysis needs with new data selection, trigger and signals processing functionalities.

### B. Monitoring Through the Web

In parallel to the online visualization provided by the dataDisplay, a set of web pages has been developed to provide over a longer time scale (some hours), but with a larger latency (half an hour), an overview of the state of the interferometer [25]. Those web pages are generated thanks to the “trend data” stream and thanks to a software environment developed for Virgo data analysis [28], VEGA, which mainly adapts to the Virgo needs the ROOT libraries developed at CERN. Thanks to the C/C++ interpreter of ROOT, a set of macros has been developed to monitor the long term evolution of the detector’s subsystems (mirrors alignment, light power inside the recycling cavity, current sensitivity, DAQ data rate, etc...). Such macros are also used now to monitor the results of glitches search algorithms, to follow the amplitude and frequency of spectral lines, to follow the evolution of the parameters used in the calibration, the level of noise in various frequency bands, the spectrograms of several useful signals, etc...

### C. Online Data Qualification

In addition to the data visualization through dataDisplay or web monitoring, a mandatory need of the Virgo experiment was to set discriminant quantities (quality flags) that summarize the state of the detector. An architecture that uses the DAQ tools has been setup to generate those quality flags, record them in the Virgo data stream and visualize them in control room.

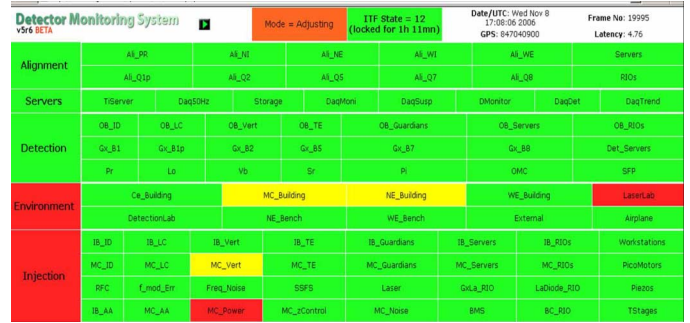


Fig. 12. Some of the quality flags visible through the web in the Virgo control room. First column shows the flags summarizing the state of each detector’s sub-system. Yellow color is a warning and red color means that, at least, one of the conditions setting the green “OK” of the flag is not fulfilled. For instance, in first column, flag “Injection” would be green only if all the sub-flags (OB\_ID, OB\_LC, etc...) are green.

For each Virgo sub-system (suspensions, photodiodes, laser injection, environment monitoring, etc...), a set of quality flags is produced online by a dedicated algorithm. Each algorithm is made of a set of conditions applied on signals. From this set of flags a global quality flag is created. Then, all the flags are displayed online through a web page (see Fig. 12) to inform control room operators about any problem detected in the interferometer or its environment [29]. In parallel, all the flags are also sent to the DAQ and stored on disk to help in the selection of data segments where the interferometer is in good conditions for data analysis.

Technically, all the detector monitoring algorithms are connected to the shared memory of a specific frames collector and use the same software implementation, the same libraries and the same type of configuration syntax. This is done thanks to a library (MoniL) developed to generate the algorithms and manage the quality flags through a configuration file, where the qualification of the data can be modulated according to the steps of the interferometer’s startup procedure.

## VII. CONCLUSION

Since summer 2001, the data acquisition of Virgo has run almost continuously, with regular improvements but without changing the main architecture, the software libraries or the standard tools chosen (VME, Ethernet, optical links, LynxOS, Linux, shared memory...). It has fulfilled its requirements for data loss minimization, latency reduction or data rate management. The software tools developed for the data collection have provided a good flexibility that has allowed for instance to connect easily new online processing tasks or online monitoring tools.

Research and development is currently done to improve the Virgo detector in the coming years. This improved detector will have faster control loops with reduced noise levels. In this perspective, an upgrade of the VME boards used for the timing distribution and for the signals optical propagation is currently under way [30]. This new “front-end” acquisition will offer more possibilities and will handle the faster control loops, maybe increasing by a factor two the data rate. However, thanks to our choice of standard tools like Ethernet network and shared memory, no new heavy development is foreseen for the



data collection or the online processing which may adapt (using faster and more numerous Linux workstations) to the new data rate and to possible new online processing requirements.

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