Prompt Interval Temporal Logic  
(extended version)

Dario Della Monica¹, Angelo Montanari², Aniello Murano¹, and Pietro Sala³

¹ Università degli Studi di Napoli “Federico II”, Napoli, Italy, dario.dellamonica@unina.it, murano@na.infn.it
² University of Udine, Udine, Italy angelo.montanari@uniud.it
³ University of Verona, Verona, Italy, pietro.sala@univr.it

Abstract. Interval temporal logics are expressive formalisms for temporal representation and reasoning, which use time intervals as primitive temporal entities. They have been extensively studied for the past two decades and successfully applied in AI and computer science. Unfortunately, they lack the ability of expressing promptness conditions, as it happens with the commonly-used temporal logics, e.g., LTL: whenever we deal with a liveness request, such as “something good eventually happens”, there is no way to impose a bound on the delay with which it is fulfilled. In the last years, such an issue has been addressed in automata theory, game theory, and temporal logic. In this paper, we approach it in the interval temporal logic setting. First, we introduce PROMPT-PNL, a prompt extension of the well-studied interval temporal logic PNL, and we prove the undecidability of its satisfiability problem; then, we show how to recover decidability (NEXPTIME-completeness) by imposing a natural syntactic restriction on it.

1 Introduction

Interval temporal logics provide a powerful framework suitable for reasoning about time. Unlike classic temporal logics, such as Linear Temporal Logic (LTL) [20] and the like, they use time intervals, instead of time points, as primitive temporal entities. Such a distinctive feature turns out to be very useful in various Computer Science and AI application domains, ranging from hardware and real-time system verification to natural language processing, from constraint satisfaction to planning [1,2,10,19,21,22]. As concrete applications, we mention TERENCE [13], an adaptive learning system for poor comprehenders and their educators (based on Allen’s interval algebra IA [1]), and RISMA [16], an algorithm to analyze behavior and performance of real-time data systems (based on Halpern and Shoham’s modal logic of Allen’s relations HS [14]).

A fundamental class of properties that can be expressed in (both interval- and point-based) temporal logics is that of liveness properties, which allow one to state that something “good” will eventually happen. However, a limitation that is common to most temporal logics is the lack of support for promptness: it is not possible to bound the delay with which a liveness request is fulfilled, despite the fact that this is desirable for many practical applications (see [15] for a convincing argument). To overcome such a shortcoming, a whole body of work has been recently devoted to the study of promptness. In [4,15], the authors extend LTL with the ability of bounding the delay with which a
temporal request is satisfied. In \cite{3}, the use of prompt accepting conditions in the context of \( \omega \)-regular automata is explored by introducing \emph{prompt-Büchi automata}, whose accepting condition imposes the existence of a bound on the number of non-accepting states in between two consecutive occurrences of accepting ones. Prompt extensions of LTL have also been investigated outside the realm of closed systems. Two-player turn-based games with perfect information have been explored in the prompt LTL setting in \cite{23}. In \cite{9}, the authors lift the prompt semantics to \( \omega \)-regular games, under the parity winning condition, by introducing \emph{finitary parity} games. They make use of the concept of distance between positions in a play that refers to the number of edges traversed in the game arena; the classical parity winning condition is then reformulated to take into consideration only those states occurring with a bounded distance. Such an idea has been generalised to deal with more involved prompt parity conditions \cite{12,18}. In the field of formal languages, promptness comes into play in \cite{6}, where \( \omega \)B-regular languages and their automata counterpart, known as \( \omega \)B-automata, are studied. Intuitively, \( \omega \)B-regular languages extend \( \omega \)-regular ones with the ability of bounding the distance between occurrences of sub-expressions in consecutive \( \omega \)-iterations, within each word of the language. Finally, an extension of alternating-time epistemic temporal logic with prompt-eventuality has been recently investigated in \cite{5}.

In this paper, we show that interval temporal logics can be successfully provided with a support for prompt-liveness specifications by lifting the work done in \cite{4,15} to the interval-based setting.

In \cite{4}, the language of LTL is enriched with \emph{parameterized} versions of temporal modalities \( F \) (eventually) and \( U \) (until), as well as of the dual modalities \( G \) (globally) and \( R \) (release). The resulting logic, called PLTL, features the following parameterized modalities: \( F_{\leq x} \), \( F_{>y} \), \( G_{\leq y} \), \( G_{>x} \), \( U_{\leq x} \), \( U_{>y} \), \( R_{\leq y} \), and \( R_{>x} \), where \( x \in X \), \( y \in Y \), and \( X \) and \( Y \) are two disjoint sets of \emph{bounding variables}. Intuitively, a formula \( F_{\leq x} \phi \) is true if \( \phi \) is satisfied within \( x \) time units, according to the valuation of \( x \) (the other parameterized modalities have an analogous interpretation). Thus, PLTL models are LTL models, i.e., words over the powerset of the set of atomic propositions, enriched with a valuation for the bounding variables in \( X \cup Y \). The satisfiability problem for PLTL is PSPACE-complete, as for LTL. The assumption that \( X \) and \( Y \) are disjoint is crucial in retaining decidability. In \cite{15}, the authors introduce the logic PROMPT-LTL, which restricts PLTL in three ways: (i) a parameterized version is introduced for the modality \( F \) only (parameterized versions of modalities \( G, U, \) and \( R \) are not included); (ii) only upper bounds appear in parameterized modalities, i.e., no subscript of the form \( >x \) occurs; (iii) there is only one bounding variable. The restriction imposed by PROMPT-LTL is less strong than it looks like: as shown in \cite{4}, operator \( F_{\leq x} \), along with the classic LTL constructs, is enough to define operators \( G_{>x}, U_{\leq x}, R_{>x} \) (i.e., all the operators involving in their subscript variables in \( X \)). As PROMPT-LTL enriches LTL with the ability of limiting the amount of time a fulfillment of an existential request (corresponding to a liveness property) can be delayed, it can be thought of as an extension of LTL with \emph{prompt liveness}. In \cite{15}, it is shown that reasoning about PROMPT-LTL is not harder than reasoning about LTL, with respect to a series of basic problems, including satisfiability (PSPACE-complete).
In the present paper, we show how to extend the logic \( \text{PNL} \) of temporal neighborhood (a well-known fragment of \( \text{HS} \) whose satisfiability problem is \( \text{NEXPTIME} \)-complete \([8]\)), with the ability of expressing prompt-liveness properties. Following the approach of \([15]\), we introduce ‘prompt’ versions (i.e., upper bounds only) of all modalities of \( \text{PNL} \). The resulting modality templates are as follows: the prompt-right-adjacency \( \langle A_x \rangle \) and the prompt-left-adjacency \( \langle \bar{A}_x \rangle \), capturing prompt-liveness in the future and in the past, respectively, as well as the dual modalities \([A_x]\) and \([\bar{A}_x]\). Intuitively, a modality \( \langle A_x \rangle \) (for some upper bound \( x \)) forces the existence of an event starting exactly when the current one terminates and ending within an amount of time bounded above by the value of \( x \). Similarly, \( \langle \bar{A}_x \rangle \) forces the existence of an event ending exactly when the current one begins and starting at most \( x \) time units before the beginning of the current one. Modalities \([A_x]\) and \([\bar{A}_x]\) express dual properties in the standard way, namely, \([A_x]\psi\) stands for \( \neg \langle A_x \rangle \neg \psi \) and \([\bar{A}_x]\psi\) stands for \( \neg \langle \bar{A}_x \rangle \neg \psi \). We name the proposed logic \( \text{PROMPT-PNL} \) (Section \([2]\)).

We first prove that the future fragment of \( \text{PROMPT-PNL} \) (\( \text{PROMPT-RPNL} \)), involving the future modalities \( \langle A \rangle \), \( \langle \bar{A} \rangle \), and \( \langle \bar{A}_x \rangle \) only, is expressive enough to encode the finite colouring problem, known to be undecidable \([17]\). Undecidability of \( \text{PROMPT-RPNL} \) (and \( \text{PROMPT-PNL} \)) immediately follows (Section \([3]\)). Notably, unlike \( \text{LTL} \), \( \text{PNL} \) is strictly more expressive than its future fragment \( \text{RPNL} \) (see \([11]\)); such a separation result holds between \( \text{PROMPT-PNL} \) and \( \text{PROMPT-RPNL} \) as well. Our undecidability result hinges on the unrestricted use of bounding variables within prompt modalities, which allows one to somehow establish tight bounds for the length of intervals. We show that decidability can be recovered by using two disjoint sets of bounding variables, one for existential modalities and the other for universal ones. Formulas of the resulting logic, which we name \( \text{PROMPT}_d^d \text{PNL} \), enjoy some useful monotonicity property, i.e., the truth of a formula \( \langle A_x \rangle \psi \) under a certain interpretation \( \sigma(x) \) of the bounding variable \( x \) implies its truth under every interpretation \( \sigma' \), with \( \sigma'(x) \geq \sigma(x) \).

This allows us to prove a small (pseudo-)model property for \( \text{PROMPT}_d^d \text{PNL} \), from which we conclude that the satisfiability problem for \( \text{PROMPT}_d^d \text{PNL} \) is \( \text{NEXPTIME} \)-complete (Section \([4]\)). Due to lack of space, most of the proofs are in Appendix.

\section{The logic PROMPT-PNL}

Let us start with some basic notions of interval-based temporal logics. A linear order \( \mathbb{D} \) is a pair \( \langle D, < \rangle \), where \( D \) is a set, called domain, whose elements are referred to as points, and \( < \) is a strict total order over \( D \). A (strongly) discrete linear order is a linear order such that there are only finitely many points in between any two points. In the rest of the paper, we tacitly assume every domain to be discrete. For the sake of simplicity, we identify the domain of a linear order with the linear order itself, e.g., we write “\( d \in \mathbb{D} \)” instead of “\( d \in D \)”. Let \( d \in \mathbb{D} \). The successors (resp., predecessors) of \( d \) in \( \mathbb{D} \) are the points \( d' \in \mathbb{D} \) such that \( d < d' \) (resp., \( d' < d \)); the immediate successor (resp., immediate predecessor) of \( d \) in \( \mathbb{D} \), denoted by \( \text{succ}_\mathbb{D}(d) \) (resp., \( \text{pred}_\mathbb{D}(d) \)), is (if any) the point \( d' \in \mathbb{D} \) such that \( d' \) is a successor (resp., predecessor) of \( d \) in \( \mathbb{D} \) and no point \( d'' \in \mathbb{D} \) exists with \( d < d'' < d' \) (resp., \( d' < d'' < d \)). Note that \( \text{succ}_\mathbb{D}(d) \) (resp., \( \text{pred}_\mathbb{D}(d) \)) is defined unless \( d \) is the greatest (resp., least) element in \( \mathbb{D} \). Given a linear
order $\mathcal{D}$ and two points $a, b \in \mathcal{D}$, with $a < b$, we denote by $[a, b]$ an interval (over $\mathcal{D}$).

The set of intervals over a linear order $\mathcal{D}$ is denoted by $\mathcal{I}(\mathcal{D})$. An interval structure (over a countable set $\mathcal{A}P$ of atomic propositions) is a pair $(\mathcal{D}, V)$, where $\mathcal{D}$ is a linear order and $V : \mathcal{I}(\mathcal{D}) \to 2^{\mathcal{A}P}$ is a valuation function, which assigns to each interval over $\mathcal{D}$ the set of atomic propositions that are true over it. Given a linear order $\mathcal{D}$ and $a, b \in \mathcal{D}$, we denote by $\mathcal{D}^{\geq a}$ (resp., $\mathcal{D}^{> a}$, $\mathcal{D}^{\leq a}$, $\mathcal{D}^{< a}$, $\mathcal{D}^{[a, b]}$, $\mathcal{D}^{(a, b]}$, $\mathcal{D}^{[a, b)}$, $\mathcal{D}^{(a, b)}$) the set of elements $d \in \mathcal{D}$ such that $d \geq a$ (resp., $d > a$, $d \leq a$, $d < a$, $a \leq d \leq b$, $a < d < b$, $a \leq d < b$, $a < d \leq b$). For instance, we denote by $\mathbb{R}^{> 0}$ the set of positive reals.

**Syntax and semantics.** Let $\mathcal{A}P$ (atomic propositions) and $X$ (bounding variables) be two countable sets. Formulas of PROMPT–PNL in negation normal form are defined as follows:

$$
\varphi ::= p | \varphi \land \varphi | \langle A \rangle \varphi | \langle \overline{A} \rangle \varphi | \langle A_x \rangle \varphi | \langle \overline{A}_x \rangle \varphi
$$

where $p \in \mathcal{A}P$ and $x \in X$. We also use other standard Boolean connectives, e.g., $\rightarrow$, and logical constants $\top$ and $\bot$, which are defined in the usual way. We denote by PROMPT–RPNL the PROMPT–PNL fragment obtained by excluding past modalities $\langle \overline{A} \rangle$, $\langle \overline{A}_x \rangle$, and $\langle \overline{A}_x \rangle$, and we write PROMPT–(R)PNL when we refer to both formalisms. In the following, we will take the liberty of writing PROMPT–(R)PNL formulas not in negation normal form when useful.

PROMPT–(R)PNL models are interval structures enriched with a valuation function for bounding variables in $X$ and a metric over the underlying domain. Formally, a model for PROMPT–(R)PNL (over $\mathcal{A}P$ and $X$) is a quadruple $(\mathcal{D}, V, \sigma, \delta)$, where $(\mathcal{D}, V)$ is an interval structure ($\mathcal{D}$ is the domain of the model), $\sigma : X \to \mathbb{R}^{> 0}$ is a valuation function for bounding variables, and $\delta : \mathcal{D} \times \mathcal{D} \to \mathbb{R}^{> 0}$ is a metric over $\mathcal{D}$ (i.e., the pair $(\mathcal{D}, \delta)$ is a metric space) satisfying the additional properties: for every $d, d', d'' \in \mathcal{D}$

(i) if $d < d' < d''$, then $\delta(d, d'') = \delta(d, d') + \delta(d', d'')$,

(ii) if $d$ has infinitely many successors in $\mathcal{D}$, then the set $\{\delta(d, d') \mid d < d'\}$ is not bounded above, and

(iii) if $d$ has infinitely many predecessors in $\mathcal{D}$, then the set $\{\delta(d, d') \mid d < d'\}$ is not bounded above.

For a model $M = (\mathcal{D}, V, \sigma, \delta)$, we let $\mathcal{D}_M = \mathcal{D}$, $V_M = V$, $\sigma_M = \sigma$, and $\delta_M = \delta$, that is, $\mathcal{D}_M$, $V_M$, $\sigma_M$, and $\delta_M$ denote the four components of $M$. A PROMPT–(R)PNL model is finite (resp., infinite) if so is its domain.

The truth value of a PROMPT–PNL formula over a model and an interval in it is inductively defined as follows:

- $M, [a, b] \models p$ if and only if $p \in V_M([a, b])$, for every $p \in \mathcal{A}P$;
- $M, [a, b] \models \neg p$ if and only if $p \not\in V_M([a, b])$, for every $p \in \mathcal{A}P$;
- $M, [a, b] \models \varphi_1 \land \varphi_2$ if and only if $M, [a, b] \models \varphi_1$ and $M, [a, b] \models \varphi_2$;
- $M, [a, b] \models \varphi_1 \lor \varphi_2$ if and only if $M, [a, b] \models \varphi_1$ or $M, [a, b] \models \varphi_2$;
- $M, [a, b] \models \langle A \rangle \varphi$ if and only if there is $c \in \mathcal{D}_M^a$ such that $M, [b, c] \models \varphi$;
- $M, [a, b] \models \langle \overline{A} \rangle \varphi$ if and only if for all $c \in \mathcal{D}_M^{> b}$ it holds $M, [b, c] \models \varphi$;
- $M, [a, b] \models \langle A_x \rangle \varphi$ if and only if there is $c \in \mathcal{D}_M^a$ such that $M, [c, a] \models \varphi$;
- $M, [a, b] \models \langle \overline{A}_x \rangle \varphi$ if and only if for all $c \in \mathcal{D}_M^{> a}$ it holds $M, [c, a] \models \varphi$;
- $M, [a, b] \models \langle A_x \rangle \varphi$ if and only if there is $c \in \mathcal{D}_M^{> a}$, with $\delta_M(b, c) \leq \sigma_M(x)$, such that $M, [b, c] \models \varphi$, for every $x \in X$;
- $M, [a, b] \models \langle \overline{A}_x \rangle \varphi$ if and only if for all $c \in \mathcal{D}_M^{< a}$, with $\delta_M(b, c) \leq \sigma_M(x)$, it holds $M, [b, c] \models \varphi$, for every $x \in X$. 
for every interpretation for every \( a, b \in [a, b] \models \langle A \rangle \varphi \) if and only if there is \( c \in \mathbb{D}_M^c \), with \( \delta_M(c, a) \leq \sigma_M(x) \), such that \( M, [c, a] \models \varphi \), for every \( x \in X \).

\( M, [a, b] \models [A] \varphi \) if and only if for all \( c \in \mathbb{D}_M^c \), with \( \delta_M(c, a) \leq \sigma_M(x) \), it holds \( M, [c, a] \models \varphi \), for every \( x \in X \).

The truth value of a PROMPT-RPNL formula is obtained, as expected, by restricting to the relevant clauses only.

In PNL, modalities \( \langle L \rangle \) and \( \langle T \rangle \), corresponding to Allen’s relations later and before, are definable as: \( \langle L \rangle \varphi \equiv \langle A \rangle \langle A \rangle \varphi \) and \( \langle T \rangle \varphi \equiv \langle A \rangle \langle A \rangle \varphi \). Additionally, in PROMPT-PNL it is possible to define the ‘prompt’ counterparts of modalities \( \langle L \rangle \) and \( \langle T \rangle \) as: \( \langle L_x \rangle \varphi \equiv \langle A_x \rangle \langle A_x \rangle \varphi \) and \( \langle T_x \rangle \varphi \equiv \langle A_x \rangle \langle A_x \rangle \varphi \). The resulting semantic interpretation for \( \langle L_x \rangle \) and \( \langle T_x \rangle \) is as follows:

\( M, [a, b] \models \langle L_x \rangle \varphi \) if and only if there is \( [c, d] \in \mathbb{I}(\mathbb{D}_M) \) such that \( b < c, \delta_M(b, c) \leq \sigma_M(x), \delta_M(c, d) \leq \sigma_M(x), \) and \( M, [c, d] \models \varphi \);

\( M, [a, b] \models \langle T_x \rangle \varphi \) if and only if there is \( [c, d] \in \mathbb{I}(\mathbb{D}_M) \) such that \( d < a, \delta_M(d, a) \leq \sigma_M(x), \delta_M(c, d) \leq \sigma_M(x), \) and \( M, [c, d] \models \varphi \).

Intuitively, a modality \( \langle L_x \rangle \), for some bounding variable \( x \), requires the existence of an event starting and ending within a bounded amount of time after the termination of the current one (modalities \( \langle T_x \rangle \) impose an analogous constraint in the past). Obviously, only \( \langle L_x \rangle \) is definable in PROMPT-RPNL (\( \langle T_x \rangle \) is not).

The globally-in-the-future modality \( [G] \) is defined as \( [G] \psi \equiv \psi \land \langle A \rangle \psi \wedge [A] \psi \), for every PROMPT-PNL formula \( \psi \); analogously the prompt-globally-in-the-future modality \( [G_x] \) is defined as \( [G_x] \psi \equiv \psi \land [A] \psi \wedge [A] \psi \), for every PROMPT-PNL formula \( \psi \) and \( x \in X \). Given a PROMPT-\((R)PNL\) model \( M \), modalities \( [G] \) and \( [G_x] \) induce the sets \( G_M^{[a,b],x} = \{ [a, b] \} \cup \{ [c, d] \in \mathbb{I}(\mathbb{D}_M) \mid b \leq c \} \) and \( G_M^{[a,b],x} = \{ [a, b] \} \cup \{ [c, d] \in \mathbb{I}(\mathbb{D}_M) \mid b \leq c \land \delta_M(c, d) \leq \sigma_M(x) \} \). We omit the subscript when it is clear from the context. For every PROMPT-\((R)PNL\) model \( M, [a, b] \in \mathbb{I}(\mathbb{D}_M) \), and PROMPT-PNL formula \( \psi \), it holds that \( M, [a, b] \models [G] \psi \) if and only if \( M, [c, d] \models \psi \) for every \( [c, d] \in G_M^{[a,b],x} \) and \( M, [a, b] \models [G_x] \psi \) if and only if \( M, [c, d] \models \psi \) for every \( [c, d] \in G_M^{[a,b],x} \). Finally, for a model \( M \) and \( [a, b] \in \mathbb{I}(\mathbb{D}_M) \), we define the length of \( [a, b] \) (in \( M \)) as the value \( \delta_M(a, b) \) and, for every \( p \in AP, \) if \( M, [a, b] \models p \), then we say that \( [a, b] \) is a \( p \)-interval (in \( M \)).

The satisfiability problem. A PROMPT-\((R)PNL\) formula \( \varphi \) is satisfiable if, and only if, there exist a PROMPT-\((R)PNL\) model \( M \) and an interval \( [x, y] \) in \( M \) such that \( M, [x, y] \models \varphi \). Moreover, a satisfiable formula is said to be finitely satisfiable if there exists a finite model for it; otherwise it is non-finitely satisfiable. The satisfiability (resp., finite satisfiability) problem for PROMPT-\((R)PNL\) consists in deciding whether a given PROMPT-\((R)PNL\) formula is satisfiable (resp., finitely satisfiable).

3 Undecidability of PROMPT-RPNL

We prove the undecidability of the satisfiability problem for the logic PROMPT-RPNL (and thus for PROMPT-PNL as well), by a reduction from the finite coloring problem (FCP) [17]. An instance of FCP (aka finite tiling problem) is a tuple \( \Delta = \langle C, H, V, c_i, c_f \rangle \), where \( C \) is a finite, non-empty set of colours, \( H, V \subseteq C \times C \) are total binary relations over the set of colours \( C \), and \( c_i, c_f \in C \) are distinguished colours. A solution
to $\Delta$ is a pair $\langle C, (K, L) \rangle$, where $K, L \in \mathbb{N}$ and $C : \{0, \ldots, K\} \times \{0, \ldots, L\} \rightarrow C$ is a colouring function such that $C(0, 0) = c_0, C(K, L) = c_L$, and, in addition,
- $(C(i, j), C(i + 1, j)) \in H$, for each $i < K$ and $j \leq L$ (horizontal constraint), and
- $(C(i, j), C(i, j + 1)) \in V$, for each $i \leq K$ and $j < L$ (vertical constraint).

FCP consists in establishing whether there are two natural numbers $K$ and $L$, and a colouring of the plane $\{0, \ldots, K\} \times \{0, \ldots, L\}$ such that horizontal and vertical constraints are fulfilled, and bottom-left and top-right colours are given. CFP is undecidable [17] Proposition 7.2. We encode CFP by means of a PROMPT-RPNL formula. The different aspects of the problem are encoded by means of (blocks of) formulas and the correctness of such partial encodings is testified by the corresponding lemmas below. Clearly, the conjunction of all these formulas is satisfiable if and only if CFP admits a solution. In what follows, we fix an interval model $M = \langle D, V, \sigma, \delta \rangle$.

For every $d \in D$ and $x \in X$, we define $[\sigma]_d(x) = \max\{\delta(d, d') \in \mathbb{R}^+ \mid d' \in D_{>d} \text{ and } \delta(d, d') \leq \sigma(x)\}$. It clearly holds that $[\sigma]_d(x) \leq \sigma(x)$ and, for every $d' \in D_{>d}$, we have that $[\delta(d, d')] \leq [\sigma](x)$ implies $[\delta(d, d')] \leq [\sigma]_d(x)$. For every $x \in X$, there is exactly one point $d' \in D_{>d}$ such that $[\delta(d, d')] = [\sigma]_d(x)$: we call such a point the $x$-canonical successor of $d$. The length of an interval $[d, d']$ is in $\mathbb{I}(D)$, where $d'$ is the $x$-canonical successor of $d$, is said to be $x$-canonical, for every $x \in X$.

Let $\text{succ-upperbound}$ be the formula $[G](\langle A \rangle \top \rightarrow \langle A_x \rangle)$, where $s \in X$.

**Lemma 1.** If $M, [a, b] \models \text{succ-upperbound}$ for some $[a, b]$, then for every $c \in D_{\geq b}$ that is not the greatest element in $D$ it holds $\delta(c, \text{succ}_{D}(c)) \leq [\sigma]_c(s)$. Moreover, let $c'$ be the $x$-canonical successor of $c$. If $c'$ is not the greatest element in $D$, then $[\sigma]_c(x) + [\sigma](s) > [\sigma](x)$, for every $x \in X$.

Let $\text{less-than}(x, y)$ be the formula $[G](\langle A \rangle \top \rightarrow \langle A_y \rangle) \wedge [G][A_x] \neg \text{aux}_{x, y}$ (it is a parametric formula to be instantiated with some $x, y \in X$).

**Lemma 2.** If $M, [a, b] \models \text{less-than}(x, y)$ for some $[a, b]$, then $\sigma(x) < [\sigma]_c(y)$ holds for every $c \in D_{\geq b}$, unless $c$ is the greatest element in $D$.

Let $\exists \text{-last}$ be the conjunction of the following formulas:

\begin{align*}
\neg \text{last} \land \langle A \rangle \text{last} \land [G](\langle A \rangle \text{last} \rightarrow \bigwedge_{p \in AP} [A](\neg p \land [A] \neg p)) & \quad (1) \\
[G](\langle A \rangle \text{last} \rightarrow [A] \neg \langle A \rangle \text{last}) & \quad (2) \\
[G](\langle \text{last} \rightarrow \langle A \rangle \text{unique} \rangle \land \langle \langle A \rangle \text{unique} \rightarrow [A] \neg \langle A \rangle \text{unique} \rangle) & \quad (3)
\end{align*}

**Lemma 3.** If $M, [a, b] \models \exists \text{-last}$ for some $[a, b]$, then there is exactly one last-interval in $G^{[a,b]}$, say $[c, d]$. Moreover, it holds $c > b$ and there is no $p$-interval starting in $c$ or after it, for every $p \in AP \setminus \{\text{last}\}$.

Let $a \in D$ and $[c, d] \in \mathbb{I}(D)$ be the unique last-interval (see Lemma 3). Given $p \in AP$, a $p$-chain starting at $a$ (or, simply, $p$-chain) is a finite sequence of $p$-intervals $[a_0, b_0], [a_1, b_1], \ldots, [a_m, b_m]$ such that $a = a_0$, $b_m = c$, and $b_i = a_{i+1}$ for every $i \in \{0, 1, \ldots, m - 1\}$. Let $\text{chain}(p, x)$ be the parametric formula, to be instantiated with some $p \in AP$ and $x \in X$, defined as the conjunction of the following ones:

\[ \text{succ-upperbound} \land \exists \text{-last} \]
Some point of the finite plane, or plane. Let plane ∈ K,L
If b interval and its length is below same number of tiles (incomplete, the problem being that rows (σ
This will guarantee that each row of our encoding features the same number of tiles.

Lemma 6. If M, [a, b] |= chain(p, x) for some {a, b}, then there is a finite p-chain starting at b whose intervals have x-canonical length. Moreover, no other p-interval exists in G[a,b]x besides the ones in such a p-chain.

We now provide an encoding of a finite plane \{0, \ldots, K\} \times \{0, \ldots, L\}, for some K, L ∈ \mathbb{N}. The idea is to use a u-chain whose intervals are either tile-intervals, encoding some point of the finite plane, or *-intervals, which are used as separators between rows of the plane. Let plane be the conjunction of the following formulas:

\begin{align*}
less-than(s, x) \land less-than(x, y) \land chain(u, x) \land chain(row, y) \\
(G((u \leftrightarrow * \lor tile) \land (* \rightarrow \neg tile)) \\
\langle A \rangle * \land [G]((\ast \rightarrow \langle A \rangle tile) \land (u \land \langle A \rangle \text{last} \rightarrow tile)) \\
(G((\langle A \rangle row \rightarrow \langle A \rangle *)) \\
\langle G \rangle (\langle A \rangle * \rightarrow [A_j]((\langle A \rangle \ast \rightarrow row))
\end{align*}

Lemma 5. If M, [a, b] |= plane for some [a, b], then there is a finite sequence of points b = p_0 < p_1 < \ldots < p_{n_1} = p_0 < p_2 < \ldots < p_{n_2} = p_0 < \ldots < p_{n_r} = p_0 < \ldots < p_{n_r}, with r ≥ 1 and n_i > 1 for every i ∈ \{1, \ldots, r\} such that: (i) [p_0, p_1] is a *-interval and its length is x-canonical, for every i ∈ \{1, \ldots, r\}; (ii) [p_j, p_{j+1}] is a tile-interval and its length is x-canonical, for every i ∈ \{1, \ldots, r\} and j ∈ \{1, \ldots, n_i - 1\}; (iii) [p_0, p_{n_r}] is a row-interval and its length is y-canonical, for every i ∈ \{1, \ldots, r - 1\}; (iv) M, [p_{n_r}, p'_1] is the unique last-interval, for some p' > p_{n_r}. Moreover, no other *-interval (resp., tile-interval) exists in G[a,b]x.

The encoding of the finite plane \{0, \ldots, K\} \times \{0, \ldots, L\} we have obtained so far is incomplete, the problem being that rows (row-intervals) do not necessarily contain the same number of tiles (tile-intervals). In order to overcome such a problem, we introduce below corr-intervals, which are used to link the i-th tile-interval of a row to the i-th tile-interval of the next row (if any) and to the i-th tile-interval of the previous row (if any). This will guarantee that each row of our encoding features the same number of tiles.

Let w-def be the conjunction of the following formulas:

\begin{align*}
less-than(x, w) \land less-than(w, y) \\
[A_y] \neg (\langle A \rangle \ast \text{-aux} \land ([\langle A \rangle] (\text{row} \land \neg (\langle A \rangle \text{last}) \rightarrow \langle A \rangle \langle A \rangle \ast \text{-aux})) \\
\langle A_x \rangle \langle A_y \rangle ([\langle A \rangle \langle \langle A \rangle \text{-last} \land [A] \langle \langle A \rangle \text{-last} \rangle \lor \langle A \rangle \ast \text{-aux})
\end{align*}

Lemma 6. If M, [a, b] |= plane \land w-def for some [a, b], then σ(w) < |σ|,c(y) ≤ σ(y) < σ(w) + σ(s) for every c ∈ \mathbb{D}^{\geq b}, unless c is the greatest element in \mathbb{D}.
Let $correspondence$ be the conjunction of the following formulas:

$$\text{plane} \land w\text{-def} \land \text{less-than}(s,z) \land \text{less-than}(z,x) \quad (19)$$

$$[G](\langle A_x \rangle u \rightarrow [A_x](\langle A_x \rangle u \text{-suffix} \land (\langle A_x \rangle u \lor \langle A \rangle \text{last}))) \quad (20)$$

$$[G_x] \neg u\text{-suffix} \quad (21)$$

$$[G](\text{row} \land \neg(\langle A \rangle \text{last}) \rightarrow corr) \quad (22)$$

$$[G](\langle A_x \rangle \text{tile} \land \langle A \rangle \langle A_x \rangle \rightarrow \langle A_y \rangle corr) \quad (23)$$

$$[G_w] \neg corr \quad (24)$$

$$[G](corr \rightarrow \langle A \rangle \text{tile}) \quad (25)$$

$$[G](\langle A_x \rangle (\langle A_x \rangle \land \langle A_x \rangle \ast) \rightarrow [A_y](corr \rightarrow \langle A_x \rangle (\langle A_x \rangle \land \langle A_x \rangle \ast))) \quad (26)$$

**Lemma 7.** If $M, [a,b] \models correspondence$ for some $[a,b]$, then $[p_i^j, p_i^{j+1}]$ is a core-interval, with $\sigma(w) < \delta(p_i^j, p_i^{j+1}) \leq \sigma(y)$, for every $i \in \{1, \ldots, r-1\}$ and $j \in \{0, \ldots, n_i - 1\}$. Moreover, for every $i \in \{1, \ldots, r-1\}$, it holds that $n_i = n_{i+1}$.

Now, let $\Delta = \langle C, H, V, c_i, c_f \rangle$ be an instance of FCP and let $\varphi_\Delta$ be the conjunction of the following formulas:

$$correspondence \land \langle A_x \rangle C \land [G_x]((\langle A_x \rangle \land \langle A \rangle \text{last}) \rightarrow c_f) \quad (27)$$

$$[G_x](\langle A_x \rangle \text{tile} \leftrightarrow \bigvee_{c \in C} c) \land [G](\bigwedge_{c,c' \in C, c \neq c'} \neg(c \land c')) \quad (28)$$

$$[G](\langle A_x \rangle (\langle A_x \rangle \land \langle A \rangle \text{tile}) \rightarrow \bigvee_{(c,c') \in H} \langle A_x \rangle (c \land \langle A_x \rangle c')) \quad (29)$$

$$[G_x]((\langle A_x \rangle \land \langle A_y \rangle \text{corr}) \rightarrow \bigvee_{(c,c') \in V} ((\langle A_x \rangle c \land [A_y](corr \rightarrow \langle A_x \rangle c')))) \quad (30)$$

**Lemma 8.** The formula $\varphi_\Delta$ is satisfiable if and only if the FCP instance $\Delta$ has a positive answer.

**Theorem 1.** The satisfiability problem for $\text{PROMPT}^d\text{-PNL}$, and thus the one for $\text{PROMPT}^d\text{-PNL}$, is undecidable.

### 4 Decidability of $\text{PROMPT}^d\text{-PNL}$

In this section, we show how to restrict the use of prompt modalities to get a fragment of $\text{PROMPT}^d\text{-PNL}$ with a decidable satisfiability problem.

We define $\text{PROMPT}^d\text{-PNL}$ as the fragment of $\text{PROMPT}^d\text{-PNL}$ obtained by using disjoint sets of bounding variables for existential and universal prompt modalities. Formally, let us partition the set $X$ of bounding variables into sets $X_\exists$ and $X_\forall$. The syntax of $\text{PROMPT}^d\text{-PNL}$ is defined as:

$$\varphi ::= p \mid \varphi \land \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi \mid \langle A \rangle \varphi$$

where $p \in AP$, $x \in X_\exists$, and $y \in X_\forall$. Since $\text{PROMPT}^d\text{-PNL}$ is a syntactic restriction of $\text{PROMPT}^d\text{-PNL}$, both formalisms share the same semantics. In particular, a $\text{PROMPT}^d\text{-PNL}$ model is a $\text{PROMPT}^d\text{-PNL}$ model as well. Analogously to the unrestricted case, we define $\text{PROMPT}^d\text{RPNL}$ as $\text{PROMPT}^d\text{-PNL}$ devoid of past modalities $\langle A \rangle$, $\langle A \rangle$, $\langle A \rangle$, and $\langle A \rangle$. 
PROMPT\textsuperscript{d}PNL is not closed under negation. For any given PROMPT\textsuperscript{d}PNL formula \( \psi \), we inductively define \( \text{neg}(\psi) \) as shown in Table 1 (\( \text{neg}(\psi) \) is not necessarily a PROMPT\textsuperscript{d}PNL formula). If \( \psi \) is a (non-prompt) PNL formula, then \( \text{neg}(\psi) \equiv \neg \psi \). Moreover, we define \( \text{neg}(\sim \psi) \) as \( \psi \) and thus we have that \( \text{neg}(\text{neg}(\psi)) \equiv \psi \), for every PROMPT\textsuperscript{d}PNL formula \( \psi \).

<table>
<thead>
<tr>
<th>\psi</th>
<th>\text{neg}(\psi)</th>
<th>\psi</th>
<th>\text{neg}(\psi)</th>
</tr>
</thead>
<tbody>
<tr>
<td>( p )</td>
<td>( \neg p )</td>
<td>( p )</td>
<td>( \neg p )</td>
</tr>
<tr>
<td>( \psi_1 \land \psi_2 )</td>
<td>( \neg \psi_1 \lor \neg \psi_2 )</td>
<td>( \psi_1 \lor \psi_2 )</td>
<td>( \neg \psi_1 \land \neg \psi_2 )</td>
</tr>
<tr>
<td>( \langle A \rangle \psi_1 )</td>
<td>( \langle A \rangle \neg \psi_1 )</td>
<td>( \langle A \rangle \psi_1 )</td>
<td>( \langle A \rangle \neg \psi_1 )</td>
</tr>
<tr>
<td>( \langle \neg A \rangle \psi_1 )</td>
<td>( \langle \neg A \rangle \neg \psi_1 )</td>
<td>( \langle \neg A \rangle \psi_1 )</td>
<td>( \langle \neg A \rangle \neg \psi_1 )</td>
</tr>
</tbody>
</table>

Table 1. Definition of \( \text{neg}(\psi) \), for a PROMPT\textsuperscript{d}PNL formula \( \psi \)

A close analysis of the proof of the undecidability of PROMPT-(R)PNL reveals that the unrestricted use of bounding variables within prompt modalities allows one to somehow establish tight bounds for the length of intervals, and this ability is crucial to the encoding. We are going to show that decidability can be recovered by not allowing both existential and universal prompt quantification on the same bounding variable. Intuitively, decidability follows from the fact that, when disjoint sets of bounding variables are used within existential and universal prompt modalities, formulas enjoy a monotonicity property, which does not hold for unrestricted PROMPT-(R)PNL formulas.

Let \( M = (\mathbb{D}, V, \sigma, \delta) \) be a PROMPT-PNL model, \( x \in X \), and \( r \in \mathbb{R}_{>0} \). We denote by \( M_{[x:r]} \) the model \( (\mathbb{D}, V, \sigma', \delta) \), where \( \sigma'(x) = r \) and \( \sigma'(x') = \sigma(x') \) for every \( x' \in X \) with \( x' \neq x \).

**Proposition 1 (monotonicity).** Let \( \psi \) be a formula of PROMPT\textsuperscript{d}PNL, \( M \) be a model of PROMPT\textsuperscript{d}PNL, and \( [a, b] \) be an interval in \( M \). If \( M_{[x:r]} \models \psi \), then \( M_{[x:r], [a, b]} \models \psi \) for all \( x \in X_\prec \) and \( r \in \mathbb{R}_{>0} \), with \( r \geq \sigma_M(x) \). In a dual fashion, if \( M_{[a, b]} \models \psi \), then \( M_{[y:r], [a, b]} \models \psi \) for all \( y \in X_\succ \) and \( r \in \mathbb{R}_{>0} \), with \( r \leq \sigma_M(y) \).

Checking that the above monotonicity property holds for PROMPT\textsuperscript{d}PNL is immediate. To see that it does not hold for PROMPT-PNL, consider the formula \( \psi = [A_p] \neg p \land \langle A_q \rangle p \land [A_r] \neg q \land \langle A_s \rangle q \). Clearly, \( \psi \) is satisfiable and all of its models are such that the value of \( x \) is bounded below by the value of \( y \) and above by the value of \( z \).

By Proposition 1 when studying the (finite) satisfiability problem for PROMPT\textsuperscript{d}PNL we can assume, w.l.o.g., that \( |X_\prec| = |X_\succ| = 1 \), as every formula \( \psi \), featuring (possibly) more than one bounding variable in \( X_\prec \) or \( X_\succ \), can be transformed into an equi-satisfiable one \( \psi' \), obtained by replacing two distinguished (chosen randomly) variables \( \hat{x} \in X_\prec \) and \( \hat{y} \in X_\succ \) for every \( x \in X_\prec \) and \( y \in X_\succ \), respectively. It is not difficult to check that, due to monotonicity, \( \psi \) is (finitely) satisfiable if and only if so is \( \psi' \). Therefore, for the remainder of the section, we set \( X_\prec = \{ x \} \) and \( X_\succ = \{ y \} \).

**Finite satisfiability.** The finite satisfiability problem for PROMPT\textsuperscript{d}PNL can be reduced to the one for plain PNL, known to be NEXPTIME-complete \cite{[8]}. Let \( \psi \) be a formula of PROMPT\textsuperscript{d}PNL and let \( \text{plain}(\psi) \) be the PNL formula obtained from \( \psi \) by:
(i) replacing existential prompt modalities by the corresponding non-prompt versions (i.e., substituting \(A\) for \(\langle A \rangle\) and \(\langle \overline{A} \rangle\) for \(\langle \overline{A} \rangle\)), and

(ii) replacing all sub-formulas of the forms \([A_y]\psi\) and \([\overline{A}_y]\psi\) by the constant \(\top\).

It is not difficult to show by induction on the structure of \(\psi\) that if \(\psi\) is finitely satisfiable, so is \(plain(\psi)\). On the other hand, if \(plain(\psi)\) is finitely satisfiable, then let \(M_{plain(\psi)} = \langle D, V \rangle\) be a PNL model such that \(M_{plain(\psi)}\{a, b\} = plain(\psi)\) for some \([a, b] \in \mathbb{I}(D)\). We define \(\delta(d, d') = \{\{d'' \in D \mid d < d'' \leq d'\}\}\) for every \(d, d' \in D\). Since \(D\) is finite, both \(\max_d = \max\{\delta(d, d') \mid d, d' \in D\}\) and \(\min_d = \min\{\delta(d, d') \mid d, d' \in D\}\) are well defined, thus we can set \(\sigma(x) = \max_d\) and \(\sigma(y) = \min_d\). It is possible to show that \(M = \langle D, V, \sigma, \delta \rangle\) is such that \(M, [a, b] \models \psi\). Therefore, \(\psi\) is finitely satisfiable, too.

**Theorem 2.** The finite satisfiability problem for \(PROMPT^d_{PNL}\) is NEXPTIME-complete.

In order to deal with formulas that are non-finitely satisfiable, in what follows we show how the search for an infinite model can be reduced to the search for a finite witness for it, within a finite search space. Decidability of the satisfiability problem for \(PROMPT^d_{PNL}\) immediately follows.

### 4.1 Prompt labeled interval structures

In this subsection we define labeled interval structures for \(PROMPT^d_{PNL}\) formulas, which are, intuitively, extended models, where intervals are labeled with sets of sub-formulas (instead of sets of atomic propositions) of the considered formula. From now on, we let \(\varphi\) be a generic \(PROMPT^d_{PNL}\) formula.

Let \(Sub(\varphi)\) be the set of all sub-formulas of \(\varphi\) and let \(Sub^\sim(\varphi) = \{neg(\psi) \mid \psi \in Sub(\varphi)\}\). The closure of \(\varphi\), denoted by \(Cl(\varphi)\), is the set \(Sub(\varphi) \cup Sub^\sim(\varphi) \cup \{\langle A \rangle \varphi, neg(\langle A \rangle \varphi)\}\). Clearly, \(|Cl(\varphi)| \leq 2 \cdot |\varphi| + 2\) holds.

A future temporal request of \(\varphi\) is a formula in \(Cl(\varphi)\) having one of the following forms: \(\langle A \rangle \psi, neg(\langle A \rangle \psi), \langle A \rangle \varphi, neg(\langle A \rangle \varphi), [A_y] \psi, neg([A_y] \psi)\), for some \(\psi\). Analogously, a past temporal request of \(\varphi\) is a formula in \(Cl(\varphi)\) having one of the following forms: \(\langle \overline{A} \rangle \psi, neg(\langle \overline{A} \rangle \psi), \langle \overline{A} \rangle \varphi, neg(\langle \overline{A} \rangle \varphi), [\overline{A}_y] \psi, neg([\overline{A}_y] \psi)\), for some \(\psi\). We denote by \(TR_f(\varphi)\) (resp., \(TR_p(\varphi)\)) the set of future (resp., past) temporal requests of \(\varphi\). In addition, the set of temporal requests of \(\varphi\), denoted by \(TR(\varphi)\), is defined as \(TR_f(\varphi) \cup TR_p(\varphi)\).

A \(\varphi\)-atom is a subset \(A\) of \(Cl(\varphi)\) such that, for every \(\psi, \psi_1, \psi_2 \in Cl(\varphi)\), (i) \(\psi \in A\) if and only if \(neg(\psi) \notin A\) and (ii) \(\psi_1 \lor \psi_2 \in A\) if and only if \(\psi_1 \in A\) or \(\psi_2 \in A\). Notice that conditions (i) and (ii) imply \(\psi_1 \land \psi_2 \in A\) if and only if \(\psi_1 \in A\) and \(\psi_2 \in A\). We denote the set of \(\varphi\)-atoms by \(A_\varphi\).

A prompt \(\varphi\)-labeled interval structure (pLIS\(\varphi\)) is a 5-tuple \(L = \langle D, L, \delta, X, Y \rangle\), where \(\langle D, \delta \rangle\) is a metric space, \(L : \mathbb{I}(D) \rightarrow A_\varphi\) is a labeling function (or simply labeling) such that \(\varphi \in L([a, b])\) for some \([a, b] \in \mathbb{I}(D)\), and \(X, Y \in \mathbb{N}\) are the existential and the universal bound, respectively. Sometimes, for the sake of brevity, we omit the last three components of the 5-tuple and we denote a pLIS\(\varphi\) as a 2-tuple \(\langle D, L \rangle\) instead. Moreover, given a pLIS\(\varphi\) \(L = \langle D, L \rangle\), we denote by \(\mathbb{D}_L\) its underlying domain \(D\) and by \(L_L\) the labeling function \(L\). A pLIS\(\varphi\) \(L\) is finite (resp., infinite) if so is \(\mathbb{D}_L\).
Given a pLIS \( L \) and a point \( d \in D_L \), we define the set of future requests of \( d \) in \( L \), denoted by \( f\)-REQ\( L \)(d), as \( \bigcup_{d' \in <d}(L_L(d', d) \cap TR_f(\varphi)) \), the set of past requests of \( d \) in \( L \), denoted by \( p\)-REQ\( L \)(d), as \( \bigcup_{d' \in >d}(L_L(d, d') \cap TR_p(\varphi)) \), and the set of requests of \( d \) in \( L \), denoted by \( \text{REQ}\( L \)(d), as \( f\)-REQ\( L \)(d) \( \cup \) \( p\)-REQ\( L \)(d). We denote by \( \text{REQ}_\varphi \) the class of all sets of requests, i.e., \( \text{REQ}_\varphi = \{ R \mid R = \text{REQ}\( L \)(d) for some pLIS \( L \) and \( d \in D_L \} \). We have that \( |\text{REQ}_\varphi| \leq 2^{2|\varphi|} \).

An existential request of \( \varphi \) is a temporal request of \( \varphi \) of one the following forms: \( \langle A \rangle \psi \), \( \langle A \rangle \psi \), \( \langle A \rangle \psi \), \( \langle A \rangle \psi \), \( \neg \langle A \rangle \psi \), and \( \neg \langle A \rangle \psi \), for some \( \psi \). A universal request of \( \varphi \) is a temporal request of \( \varphi \) that is not an existential one. Let \( L = \langle D, L, \delta, X, Y \rangle \) be a pLIS \( \varphi \) and \( d \in D \). We define \( \exists\)-REQ\( L \)(d) = \{ \psi \in \text{REQ}\( L \)(d) \mid \psi \text{ is an existential request of } \varphi \} \) and \( \forall\)-REQ\( L \)(d) = \text{REQ}\( L \)(d) \( \setminus \exists\)-REQ\( L \)(d).

For \( \psi \in \exists\)-REQ\( L \)(d), we say that \( \psi \) is fulfilled in \((L, d)\) by \( d' \in D \) if, and only if, one of the following holds:

- \( \psi = \langle A \rangle \psi' \) for some \( \psi' \) and \( \psi' \in L([d, d']) \),
- \( \psi = \langle A \rangle \psi' \) for some \( \psi' \) and \( \psi' \in L([d', d]) \),
- \( \psi = \langle A \rangle \psi' \) for some \( \psi' \) and \( \psi' \in L([d', d']) \), and \( \delta(d, d') \leq X \),
- \( \psi = \langle A \rangle \psi' \) for some \( \psi' \) and \( \psi' \in L([d, d']) \), and \( \delta(d', d) \leq X \),
- \( \psi = \neg \langle A \rangle \psi' \) for some \( \psi' \) and \( \neg \langle A \rangle \psi' \in L([d, d']) \), and \( \delta(d, d') \leq Y \),
- \( \psi = \neg \langle A \rangle \psi' \) for some \( \psi' \) and \( \neg \langle A \rangle \psi' \in L([d', d]) \), and \( \delta(d, d') \leq Y \).

\( \psi \) is fulfilled in \((L, d)\) if and only if there is \( d' \) such that \( \psi \) is fulfilled in \((L, d)\) by \( d' \).

For \( \psi \in \forall\)-REQ\( L \)(d), we say that \( \psi \) is fulfilled in \((L, d)\) if, and only if, one of the following holds:

- \( \psi = [A] \psi' \) for some \( \psi' \) and \( \psi' \in L([d, d']) \) for every \( d' \in D^{>d} \),
- \( \psi = [A] \psi' \) for some \( \psi' \) and \( \psi' \in L([d', d]) \) for every \( d' \in D^{<d} \),
- \( \psi = [A] \psi' \) for some \( \psi' \) and \( \psi' \in L([d, d']) \) for every \( d' \in D^{>d} \) with \( \delta(d, d') \leq Y \),
- \( \psi = [A] \psi' \) for some \( \psi' \) and \( \psi' \in L([d', d]) \) for every \( d' \in D^{<d} \) with \( \delta(d, d') \leq Y \),
- \( \psi = \neg [A] \psi' \) for some \( \psi' \) and \( \neg [A] \psi' \in L([d, d']) \) for every \( d' \in D^{>d} \) with \( \delta(d, d') \leq X \),
- \( \psi = \neg [A] \psi' \) for some \( \psi' \) and \( \neg [A] \psi' \in L([d', d]) \) for every \( d' \in D^{<d} \) with \( \delta(d, d') \leq X \).

\( \psi \) is \( \exists \)-fulfilled in \((L, d)\) if, and only if, every \( \psi \in \exists\)-REQ\( L \)(d) is fulfilled; \( \psi \) is \( \forall \)-fulfilled in \((L, d)\) if, and only if, every \( \psi \in \forall\)-REQ\( L \)(d) is fulfilled; \( \psi \) is fulfilled in \((L, d)\) if, and only if, it is both \( \exists \)- and \( \forall \)-fulfilled in \((L, d)\).

An existentially fulfilling (resp., universally fulfilling, fulfilling) pLIS \( \varphi \), aka \( \exists\)-pLIS \( \varphi \) (resp., \( \forall\)-pLIS \( \varphi \), \( \forall\)-pLIS \( \varphi \)), is a pLIS \( \varphi \) \( L \) such that every \( d \in D_L \) is \( \exists \)-fulfilled (resp., \( \forall \)-fulfilled, fulfilled) in \((L, d)\).

**Proposition 2.** \( \varphi \) is satisfiable if and only if there exists a \( \exists\)-pLIS \( \varphi \), and it is finitely satisfiable if and only if there exists a finite \( \exists\)-pLIS \( \varphi \).

Before showing the decidability of \( \text{PROMPT}^d_{\text{PNL}} \), we prove a result that will later come in handy. A set of requests \( \text{REQ}\( L \)(d) \) for a pLIS \( L \) and \( d \in D_L \) is consistent if for each \( \psi \in \text{REQ}\( L \)(d) \), we have that \( \neg \psi \notin \text{REQ}\( L \)(d) \); otherwise, it is inconsistent.

**Proposition 3.** Let \( L \) be a pLIS \( \varphi \) and \( d \in D_L \). The following properties hold, unless \( \text{REQ}\( L \)(d) \) is inconsistent:
4.2 A bounded witness for non-finitely satisfiable formulas

Let \( L \) be a pLIS \( \phi \) and \( d \in D_L \). A set of essentials of \( d \) (in \( L \)) is any minimal (with respect to set inclusion) set \( E \subseteq D_L \) such that for every \( \psi \in \exists\-\text{REQ}^L(d) \) there is \( d' \in E \) for which \( \psi \) is fulfilled in \( (L, d) \) by \( d' \). We denote by \( \mathcal{E}_L(d) \) the class containing all sets of essentials of \( d \) in \( L \), i.e., \( \mathcal{E}_L(d) = \{E \subseteq D_L \mid E \text{ is a set of essentials of } d \text{ in } L\} \).

Intuitively, a set of essentials of \( d \) is a collection of points that jointly make \( d \exists\)-fulfilled in \( L \). Clearly \( \mathcal{E}_L(d) \neq \emptyset \) if and only if \( d \exists\)-fulfilled in \( L \). We lift this concept to a higher order: a set of essentials of essentials (or 2nd-order essentials) of \( d \) (in \( L \)) is any minimal (with respect to set inclusion) set \( E_2 \subseteq D_L \) such that (i) \( E_1 \subseteq E_2 \) for some \( E_1 \in \mathcal{E}_L(d) \) and (ii) for every \( d' \in E_1 \) there is \( E_{d'} \in \mathcal{E}_L(d') \) for which \( E_{d'} \subseteq E_2 \). We denote by \( \mathcal{E}_2^L(d) \) the class containing all sets of 2nd-order essentials of \( d \) in \( L \), i.e., \( \mathcal{E}_2^L(d) = \{E \subseteq D_L \mid E \text{ is a set of 2nd-order essentials of } d \text{ in } L\} \).

**Definition 1** (representative). Let \( L \) be a finite pLIS \( \phi \) and \( d \in D_L \).

- If \( d \notin \{\min D_L, \max D_L\} \), then a representative of \( d \) in \( L \) is a point \( e \in D_L \) such that \( \text{REQ}^L(d) = \text{REQ}^L(e) \), \( e \) is fulfilled in \( L \), and so are points in \( E_2 \), for some \( E_2 \in \mathcal{E}_2^L(e) \) with \( E_2 \cap \{\min D, \max D\} = \emptyset \).

- If \( d = \min D_L \) (resp., \( d = \max D_L \)), then a representative of \( d \) in \( L \) is a point \( e \in D_L \) that is a representative of \( d' \) in \( L \) for some \( d' \in D_L \), with \( \text{p-REQ}^L(d') = \text{p-REQ}^L(d) \) (resp., \( \text{f-REQ}^L(d') = \text{f-REQ}^L(d) \)).

A convex subset of a domain \( D \) is a subset \( D' \) of \( D \) such that for every \( d', d'' \in D' \) and \( d \in D \), if \( d' < d < d'' \), then \( d \in D' \). A right-convex (resp., left-convex) subset of a domain \( D \) is a convex subset \( D' \) of \( D \) such that max \( D \in D' \) (resp., min \( D \in D' \)).

Given a pLIS \( L \) and \( D' \subseteq D_L \), we let request-sets \( \text{REQ}^L(d') = \{R \mid \text{REQ}^L(d) = R \text{ for some } d \in D'\} \).

**Definition 2** (left- and right-periodic pLIS \( \phi \)). Let \( L \) be a finite pLIS \( \phi \). A left-period for \( L \) is a left-convex subset \( \mathbb{E} \) of \( D_L \) such that, for every \( d \in \mathbb{E} \), if \( d \) is not fulfilled in \( L \) or \( d = \min \mathbb{E} \), then there is \( d' \in E^{>d} \) for which the following holds:

- \( d' \) is a representative of \( d \) in \( L \);
- request-sets \( \text{REQ}^L(E \setminus \{ \min \mathbb{E} \}) = \text{equal to request-sets} \( \text{REQ}^L(E^{<d'} \setminus \{ \min \mathbb{E} \}) \), which is equal to request-sets \( \text{REQ}^L(E^{<d'}) \) and there are \( d'' \in E^{<d'} \setminus \{ \min \mathbb{E} \} \) and \( d''' \in E^{>d'} \) such that \( \text{p-REQ}^{L'}(\min \mathbb{E}) = \text{p-REQ}^{L'}(d'') = \text{p-REQ}^{L'}(d''') \);
- \( \lambda \) every \( \langle A \rangle \psi \in \text{f-REQ}^L(d') \) is fulfilled by a point belonging to \( \mathbb{E} \).

A right-period for \( L \) is defined symmetrically.

**Definition 3** (\( \phi \)-witness). A \( \phi \)-witness is a finite, periodic \( \forall \neg\text{pLIS}_\phi L \), such that every \( d \in D_L \setminus (E \cup F) \) is fulfilled in \( L \), where \( E \) and \( F \) are, respectively, a left- and a right-period for \( L \), with \( E \cap F = \emptyset \) and \( D_L \setminus (E \cup F) \neq \emptyset \).
Lemma 9. An infinite ∃∀-pLIS \( L = \langle D, \mathcal{L}, \delta, \mathcal{X}, \mathcal{Y} \rangle \) exists if and only if a \( \varphi \)-witness \( L' = \langle D', \mathcal{L}', \delta', \mathcal{X}', \mathcal{Y}' \rangle \) exists.

Thanks to the previous lemma, we can reduce the search for an infinite model for a formula to the search for a finite witness. However, since such a finite witness can be arbitrarily large, the search space is still infinite. In what follows, we provide a bound on the size of the finite witness, thus obtaining a finite search space. Decidability of PROMPT\(^d\)-PNL immediately follows.

Let \( B_\varphi = |\text{REQ}_\varphi| \cdot (2 \cdot |\text{CL}(\varphi)|^2 + 2 \cdot |\text{CL}(\varphi)|) + |\text{REQ}_\varphi| \cdot |\text{CL}(\varphi)| + |\text{CL}(\varphi)| \).

Lemma 10. Let \( L = \langle D, \mathcal{L}, \delta, \mathcal{X}, \mathcal{Y} \rangle \) be a \( \varphi \)-witness, \( E \) and \( F \) being, respectively, a left- and a right-period for it. If \( |E| > B_\varphi \) (resp., \( |F| > B_\varphi \), \( |D \setminus (E \cup F)| > B_\varphi \)), then there is a \( \varphi \)-witness \( L' = \langle D', \mathcal{L}', \delta', \mathcal{X}', \mathcal{Y}' \rangle \) with \( |D'| = |D| - 1 \).

The size of a pLIS \( \varphi \)-L exists if and only if there is one of size at most \( 3 \cdot B_\varphi \leq 3 \cdot (2^2 |\varphi| + 2 \cdot (2 \cdot |\varphi| + 2)^2 + 2 \cdot (2 \cdot |\varphi| + 2)) + 2^2 |\varphi| + 2 \cdot (2 \cdot |\varphi| + 2) \).

Theorem 3. The satisfiability problem for PROMPT\(^d\)-PNL is NEXPTIME-complete.

5 Conclusions

In this paper, we have studied the problem of enriching the well-known propositional logic of temporal neighborhood PNL with support for prompt-liveness specifications. We first proved that the logic obtained from PNL by introducing “prompt” versions of its modalities with no restriction on the use of bounding variables, that we call PROMPT-PNL, is undecidable. Then, we showed that decidability can be recovered by introducing a partition of bounding variables into two classes, one for the existential modalities, the other for the universal ones. The satisfiability problem for the resulting logic, named PROMPT\(^d\)-PNL, is indeed NEXPTIME-complete.

The work done can be further developed in various directions.

First, we are interested in identifying the minimum number of bounding variables that suffice to make PROMPT-PNL undecidable. We believe it possible to prove that when the set of variables is small enough, e.g., when it includes two bounding variables only, the logic is still expressive enough to capture some meaningful promptness conditions and remains decidable.

We also aim at investigating the more powerful setting of parametric extensions of PNL. Parametric PNL can be viewed as a natural generalization of PROMPT-PNL, as parametric modalities allow one to express both lower and upper bounds on the delay with which a request is fulfilled (PROMPT-PNL only copes with the latter).

Last but not least, we are interested in comparing the expressiveness of the logics PROMPT-PNL and PROMPT\(^d\)-PNL with that of metric PNL, that is, the metric extension of PNL introduced and systematically studied in [7].
References

A Proofs of Section 3

Lemma 1. If $M, [a, b] \models \text{succ-upperbound} \; \text{for some} \; [a, b]$, then for every $c \in \mathbb{D}^\geq b$ that is not the greatest element in $\mathbb{D}$ it holds $\delta(c, \text{succ}_D(c)) \leq [\sigma]_c(s)$. Moreover, let $c'$ be the $x$-canonical successor of $c$. If $c'$ is not the greatest element in $\mathbb{D}$, then $[\sigma]_c(x) + \sigma(s) > \sigma(x)$, for every $x \in X$.

Proof. Let $c \in \mathbb{D}^\geq b$ and assume that $c$ is not the greatest element in $\mathbb{D}$. Let $\text{succ}_D(d)$ be the result of applying $i$ times $\text{succ}_D$ to $d$, for every $d \in \mathbb{D}$ and $i \in \mathbb{N}$. Since $M, [a, b] \models \text{succ-upperbound}$, there is $d \in \mathbb{D}^\geq c$, with $\delta(c, d) \leq \sigma(s)$ (and thus $\delta(c, d) \leq [\sigma]_c(s)$ holds as well), and, by the definition of $[\sigma]_c(s)$, it holds $\delta(c, \text{succ}_D(c)) \leq \delta(c, d) \leq [\sigma]_c(s)$.

To prove the second part of the claim, observe that, by the definition of $[\sigma]_c(x)$, $\delta(c, \text{succ}_D(c')) > \sigma(x)$ holds. Since $\delta(c, \text{succ}_D(c')) = \delta(c, c') + \delta(c', \text{succ}_D(c'))$ and $\delta(c', \text{succ}_D(c')) \leq [\sigma]_c(s) \leq \sigma(s)$, we conclude that $[\sigma]_c(x) + \sigma(s) \geq \delta(c, c') + \delta(c', \text{succ}_D(c')) = \delta(c, \text{succ}_D(c')) > \sigma(x)$.

Lemma 2. If $M, [a, b] \models \text{less-than}(x, y)$ for some $[a, b]$, then $\sigma(x) < [\sigma]_c(y)$ holds for every $c \in \mathbb{D}^\geq b$, unless $c$ is the greatest element in $\mathbb{D}$.

Proof. Let $c \in \mathbb{D}^\geq b$ and let us assume that $c$ is not the greatest element in $\mathbb{D}$. By the first conjunct of $\text{less-than}(x, y)$, there exists $d \in \mathbb{D}^\geq c$, with $\delta(c, d) \leq \sigma(y)$ (and thus $\delta(c, d) \leq [\sigma]_c(y)$ holds as well), such that $M, [c, d] \models \text{aux}_{x,y}$. By the second conjunct, if $\delta(c, d) \leq \sigma(x)$, then $M, [c, d] \models \neg \text{aux}_{x,y}$. Thus, it must be $\delta(c, d) > \sigma(x)$, and $\sigma(x) < [\sigma]_c(y)$ follows immediately.

Lemma 3. If $M, [a, b] \models \exists\text{-last} \; \text{for some} \; [a, b]$, then there is exactly one last-interval in $G^{[a, b]}$, say it $[c, d]$. Moreover, it holds $c > b$ and there is no $p$-interval starting in $c$ or after it, for every $p \in \mathcal{AP} \setminus \{\text{last}\}$.

Proof. By the second conjunct of (1) there is a last-interval $[c, d]$, with $c \in \mathbb{D}^\geq b$. By the first conjunct of (1), (2), and (3), there is no other last-interval in $G^{[a, b]}$. Finally, due to the third conjunct of (1), for every $p \in \mathcal{AP}$ there is no $p$-interval starting in $c$ or after it.

Lemma 4. If $M, [a, b] \models \text{chain}(p, x)$ for some $[a, b]$, then there is a finite $p$-chain starting at $b$ whose intervals have $x$-canonical length. Moreover, no other $p$-interval exists in $G^{[a, b], x}$ besides the ones in such a $p$-chain.

Proof. By (4) and Lemma [1] $[\sigma]_c(x)$ is defined for every $c \in \mathbb{D}^\geq b$ and $x \in X$, unless $c$ is the greatest element in $\mathbb{D}$. By (4) and Lemma [3] there is exactly one last-interval in $G^{[a, b]}$, say it $[c, d]$, and we have that $c > b$. By (4), there is a $p$-chain $[a_1, b_1], [a_2, b_2], \ldots$ starting at $b$ and such that $\delta(a_i, b_i) \leq [\sigma]_c(x)$ for every $i$. Since there are only finitely many points in between $b$ and $c$, there is an index $m$ for which $b_m \geq c$. If $b_m > c$, then $M, [a_m, b_m] \models p \wedge \neg\langle A \rangle$ last and, according to (5), a $p$-interval starts at $b_m$, thus after the beginning of the unique last-interval $[c, d]$. This is in contradiction with Lemma [3]. Thus, it must be $b_m = c$, and the $p$-chain is finite, $[a_m, b_m]$ being its last interval.
We show now that, for every $i$, $[a_i, b_i]$ has $x$-canonical length, that is, $\delta(a_i, b_i) = [\sigma]_{a_i}(x)$. By construction, we already have $\delta(a_i, b_i) \leq [\sigma]_{a_i}(x)$. In order to show that $\delta(a_i, b_i) \geq [\sigma]_{a_i}(x)$ holds as well we assume, towards a contradiction, that there is a $p$-interval $[a', b'] \in G^{[a, b], x}$, such that $\delta(a', b') < [\sigma]_{a'}(x)$. By [11], $[a', b']$ is a $p_1$- or a $p_2$- interval as well. We assume, without loss of generality, that it is a $p_1$-interval. Let $c' \in \mathbb{D}$ be such that $\delta(a', c') = [\sigma]_{a'}(x)$ (the existence of such a point follows from the fact that $[\sigma]_{a'}(x)$ is well-defined). Due to [12], $[c', d']$ is a $p_1$-interval for every $d' \in \mathbb{D}^{x,c'}$ and, due to [13], $[b', c']$ is a $p_2$- interval (notice that it clearly holds $\delta(b', c') \leq [\sigma](x)$). This leads to a contradiction with [14], since the interval $[a', b']$ satisfies $p_1$ but it does not satisfy $\neg \langle A \rangle p_1$. Therefore, we can conclude that the length of every $p$-interval $[a', b'] \in G^{[a, b], x}$ is $x$-canonical, i.e., $\delta(a', b') = [\sigma]_{a'}(x)$.

To complete the proof, we have to show that there is no other $p$-interval in $G^{[a, b], x}$. Once again, let us assume, towards a contradiction, that there is a $p$-interval $[a', b'] \in G^{[a, b], x}$ such that $[a', b'] \neq [a_i, b_i]$ for any $i \in \{1, \ldots, m\}$. As we have just shown, $[a', b'] \in G^{[a, b], x}$ implies $\delta(a', b') = [\sigma]_{a'}(x)$. Therefore, in order for $[a', b']$ to exist, it must be $a_i < a' < b_i$ for some $i \in \{1, \ldots, m\}$. But this contradicts [15], because any interval ending at $a_i$ satisfies $\langle A \rangle p$ but it does not satisfy $\langle A \rangle \neg p$ (as $[a_i, a']$ satisfies $\neg p$ and $\langle A \rangle p$).

As a last note, let us point out that we needed to introduce the auxiliary atomic propositions $p_1$ and $p_2$ to avoid the following inconsistency. Suppose we replace $p$ (resp., $p^+, p^-$) for $p_1$ (resp., $p_1^+, p_1^-$) in [12], [13], and [14] and let $[a_{i-1}, b_{i-1}]$ and $[a_i, b_i]$ be two consecutive intervals in the $p$-chain (thus, $b_{i-1} = a_i$). Then, by [12], $[\text{succ}_{D}(a_i), a'_i]$ is a $p^+$-interval for every $a' \in \mathbb{D}^{\text{succ}_{D}(a_i)}$, and, by [13], $[a_i, \text{succ}_{D}(a_i)]$ is a $p^-$-interval. Thus, [14] is contradicted, as $[a_{i-1}, b_{i-1}]$ satisfies $p$ but it does not satisfy $\neg \langle A \rangle p$.

A graphical account of how formula $\text{chain}(p, x)$ works is given in Figure 4.

**Lemma 5.** If $M, [a, b] \models \text{plane}$ for some $[a, b]$, then there is a finite sequence of points $b = p_0^r < p_1^r < \ldots < p_n^r = p_{n+1}^r < p_{n+2}^r < \ldots < p_{r-1}^r = p_0^r < \ldots < p_{r-1}^r$, with $r \geq 1$ and $n_i > 1$ for every $i \in \{1, \ldots, r\}$ such that: (i) $[p_0^r, p_1^r]$ is a
\(*)\text{-interval and its length is } x\text{-canonical, for every } i \in \{1,\ldots,r\}; \ (ii) \ [p_j^i, p_j^{i+1}] \text{ is a tile-}
\text{-interval and its length is } x\text{-canonical, for every } i \in \{1,\ldots,r\} \text{ and } j \in \{1,\ldots,n_i - 1\}; \ (iii) \ [p_0^i, p_0^{i+1}] \text{ is a row-}
\text{-interval and its length is } y\text{-canonical, for every } i \in \{1,\ldots,r - 1\}; \ (iv) M, [p_{n_r}^r, p'_r] \text{ is the unique last-}
\text{interval, for some } p'_r > p_{n_r}^r. \text{ Moreover, no other}
\text{\(*)\text{-interval (resp., tile-interval) exists in } G^{[a,b],x}.} \\

Proof. \text{The last two conjuncts of (11) force the existence of a } u\text{- and a row-chain, whose}
\text{intervals’ length is } x\text{- and } y\text{-canonical, respectively (Lemma 4). Moreover, due to the}
\text{first two conjuncts of (11), we have that } \sigma(x) \leq \sigma(s) < \sigma(y) \leq \sigma(y) \text{ holds for every } c \in \mathbb{D}^{\geq b}, \text{unless } c \text{ is the greatest element in } \mathbb{D} \text{ (Lemma 3).} \\

By (12), every } u\text{-interval is either a } \ast\text{- or a tile-interval (it cannot satisfy both } \ast\text{ and tile)}, \text{ and, by (13), we have that the first (resp., last) } u\text{-interval of the } u\text{-chain is a}
\text{\ast\text{-interval (resp., tile-interval) and that every } \ast\text{-interval is followed by a tile-interval.}
\text{Thus, there are suitable values for } r, n_1, \ldots, n_r, \text{ with } r \geq 1 \text{ and } n_i > 1 \text{ for every}
\text{ } i \in \{1,\ldots,r\}, \text{ such that the } u\text{-chain yields a sequence of points}
\text{ } p_0^i < \ldots < p_{n_1}^i < \ldots < p_0^r < \ldots < p_{n_r}^r, \text{ that satisfies items } (i), (ii), \text{ and } (iv) \text{ of the lemma. From (12) it}
\text{also follows that no other } \ast\text{-interval (resp., tile-interval) exists in } G^{[a,b],x}. \\

\text{We show now that the } u\text{-chain can only be arranged in a way that item (iii) is}
\text{fulfilled as well. Let us denote the } u\text{-chain by } [a_1, b_1], [a_2, b_2], \ldots, [a_m, b_m]. \text{ We want to show that }
\text{ } m = r \text{ and } [a_i, b_i] = [p_0^i, p_{n_i}^i] \text{ for every } i \in \{1,\ldots,r\}. \text{ From (14), it}
\text{clearly follows that every } u\text{-intervals ends where the next } \ast\text{-interval starts (} m \text{ immediately follows}
\text{from that). Assume, towards a contradiction, that there is } i \in \{1,\ldots,m\} \text{ such that }
\text{ } a_i = p_0^i \text{ (for some } j \in \{1,\ldots,r\}) \text{ but } b_i \neq p_{n_i}^i. \text{ If } b_i < p_{n_i}^i, \text{ then a } u\text{-interval}
\text{starts at } b_i, \text{ but no } \ast\text{-interval starts there, yielding a contradiction with (14). If, on the}
\text{other hand, } b_i > p_{n_i}^i, \text{ then by (15) } [a_i, p_{n_i}^i] \text{ is a row-interval besides the ones in the}
\text{row-chain, yielding a contradiction with Lemma 4. Therefore, item (iii) is satisfied as}
\text{well.} \\

\text{Lemma 6. If } M, [a, b] \models \text{plane } \land \text{ } w\text{-def for some } [a, b], \text{ then } \sigma(w) < |\sigma|c(y) \leq
\text{ } \sigma(y) < \sigma(w) + \sigma(s) \text{ for every } c \in \mathbb{D}^{\geq b}, \text{unless } c \text{ is the greatest element in } \mathbb{D}. \\

Proof. \text{Let } c \in \mathbb{D}^{\geq b} \text{ be a point that is not the greatest element in } \mathbb{D}. \text{ The inequalities}
\text{ } \sigma(w) < |\sigma|c(y) \leq \sigma(y) \text{ trivially hold by (16) and Lemma 2. In order to prove that}
\text{ } \sigma(y) < \sigma(w) + \sigma(s) \text{ holds as well, we proceed as follows. By (17), unless the } u\text{-chain}
\text{(whose existence is guaranteed by Lemma 5) features only one row-interval (} r = 1 \text{ in}
\text{Lemma 5), there is a } \ast\text{-aux-interval starting after the end of the first row-interval}
\text{(with no } \ast\text{-aux-interval starting before, or at the end of, the first row-interval). By (18),}
\text{there is an interval } [p', p''], \text{ with } p' > p_0^r, \delta(p_0^r, p') \leq \sigma(s), \text{ and } \delta(p', p'') \leq \sigma(w). \text{Formula}
\text{(18) also forces } [p', p''] \text{ to end after the end of the first row-interval (i.e., } p'' > p_0^r), \text{ by requiring either that } p'' \text{ is located after the beginning of the unique last-interval}
\text{(left-hand side of the disjunction in (18), to deal with the case when the } u\text{-chain}
\text{features one row-interval only) or that a } \ast\text{-aux-interval starts at } p'' \text{ (right-hand side of the}
\text{disjunction in (18), to deal with the case when the } u\text{-chain features more than one}
\text{aux-interval).} \\

\text{Lemma 6. If } M, [a, b] \models \text{plane } \land \text{ } w\text{-def for some } [a, b], \text{ then } \sigma(w) < |\sigma|c(y) \leq
\text{ } \sigma(y) < \sigma(w) + \sigma(s) \text{ for every } c \in \mathbb{D}^{\geq b}, \text{unless } c \text{ is the greatest element in } \mathbb{D}. \\

Proof. \text{Let } c \in \mathbb{D}^{\geq b} \text{ be a point that is not the greatest element in } \mathbb{D}. \text{ The inequalities}
\text{ } \sigma(w) < |\sigma|c(y) \leq \sigma(y) \text{ trivially hold by (16) and Lemma 2. In order to prove that}
\text{ } \sigma(y) < \sigma(w) + \sigma(s) \text{ holds as well, we proceed as follows. By (17), unless the } u\text{-chain}
\text{(whose existence is guaranteed by Lemma 5) features only one row-interval (} r = 1 \text{ in}
\text{Lemma 5), there is a } \ast\text{-aux-interval starting after the end of the first row-interval}
\text{(with no } \ast\text{-aux-interval starting before, or at the end of, the first row-interval). By (18),}
\text{there is an interval } [p', p''], \text{ with } p' > p_0^r, \delta(p_0^r, p') \leq \sigma(s), \text{ and } \delta(p', p'') \leq \sigma(w). \text{Formula}
\text{(18) also forces } [p', p''] \text{ to end after the end of the first row-interval (i.e., } p'' > p_0^r), \text{ by requiring either that } p'' \text{ is located after the beginning of the unique last-interval}
\text{(left-hand side of the disjunction in (18), to deal with the case when the } u\text{-chain}
\text{features one row-interval only) or that a } \ast\text{-aux-interval starts at } p'' \text{ (right-hand side of the}
\text{disjunction in (18), to deal with the case when the } u\text{-chain features more than one}
row-interval). We need to distinguish the two cases because in the former one it is not possible for $p''$ to be the starting point of a $*$-aux-interval (as in this case the first row-interval is immediately followed by the unique last-interval, and thus no $*$-aux-interval starts after it), while in the latter case it is not possible for $p''$ to be located after the beginning of the unique last-interval (as this would make $[p', p'']$ longer than $\sigma(w)$). It is easy to see that the following holds: $\delta(p', p'') = \delta(p_0^1, p_{n_1}^1) - \delta(p_0^1, p') + \delta(p_{n_1}^1, p'')$.

Since $\delta(p_0^1, p_{n_1}^1) + \delta(p_{n_1}^1, p'') > \sigma(y)$ and $\delta(p_0^1, p') \leq \sigma(s)$, we have that $\sigma(w) \geq \delta(p', p'') > \sigma(y) - \sigma(s)$, which implies $\sigma(y) < \sigma(w) + \sigma(s)$.

A graphical account of how formula $w$-def works is given in Figure 2.\[\square\]

\[
(A_i \land \lnot A_i) \rightarrow (A_i \rightarrow \lnot \lnot A_i)
\]

\[
\begin{array}{c}
\forall \sigma \in \mathbb{D}^* \exists \text{ aux row} \exists \sigma_i(x) \exists \sigma_i(y) \exists \sigma_i(z) \exists \sigma_i(w) \exists \sigma_i(s) \exists \sigma_i(\lnot \lnot A_i) \exists \sigma_i(A_i) \exists \sigma_i(\lnot A_i) \exists \sigma_i(\lnot \lnot A_i) \exists \sigma_i(A_i) \exists \sigma_i(\lnot \lnot A_i)
\end{array}
\]

Fig. 2. A graphical explanation of how formula $w$-def force $w$ to be equal to $y - 1$. In particular, the case of multiple row-labelled intervals is depicted.

**Lemma 7.** If $M, [a, b] \models \text{ correspondence for some } [a, b]$, then $[p_j^i, p_{j+1}^i]$ is a corr-interval, with $\sigma(w) < \delta(p_j^i, p_{j+1}^i) \leq \sigma(y)$, for every $i \in \{1, \ldots, r - 1\}$ and $j \in \{0, \ldots, n_i - 1\}$. Moreover, for every $i \in \{1, \ldots, r - 1\}$, it holds that $n_i = n_{i+1}$.

**Proof.** First, we observe that for every $c \in \mathbb{D}$ that is not the greatest element in $\mathbb{D}$ it holds $\sigma(s) < [\sigma]_i(z) \leq \sigma(z) < [\sigma]_i(x) \leq \sigma(x)$ (by (19) and Lemma 3). Formulas (20) and (21) force, for every u-interval, the existence of suffixes that satisfy u-suffix and whose length is suitably bounded. More precisely, let $q_j^i \in \mathbb{D}^{\geq p_j^i}$ be such that $\delta(p_j^i, q_j^i) = [\sigma]_j(p_j^i)$, for every $i \in \{1, \ldots, r\}$ and $j \in \{0, \ldots, n_i - 1\}$. Then, $[q_j^i, p_{j+1}^i]$ is a u-suffix-interval, and both $\sigma(s) < \delta(p_j^i, q_j^i) \leq \sigma(z)$ and $\sigma(s) < \delta(q_j^i, p_{j+1}^i) \leq \sigma(z)$ hold.

The proof is by induction on $j$. Due to (19), (22), and Lemma 3, $[p_0^i, p_{i+1}^i]$ is a corr-interval for every $i \in \{1, \ldots, r - 1\}$, and thus the lemma is satisfied for $j = 0$. In order to proof the inductive case, we proceed as follows. Due to (23), for every $i \in \{1, \ldots, r - 1\}$ and $j \in \{1, \ldots, n_i - 1\}$ we have that $[p_j^i, p_j^i]$ is a corr-interval for some $p'$, with $\delta(p_j^i, p') \leq \sigma(y)$. Moreover, due to (24), we have that $\delta(p_j^i, p') > \sigma(w)$. We show that $p' = p_{j+1}^i$. Suppose, towards a contradiction, that this is not the case. We distinguish two cases.

- If $p' > p_{j+1}^i$, then it must be $p' \geq p_{j+1}^i$ and the following holds: $\delta(p_j^i, p') \geq \delta(p_j^i, p_{j+1}^i) = \delta(p_j^i, p_{j+1}^i) - \delta(p_{j-1}^i, p_j^i) + \delta(p_{j-1}^i, q_{j+1}^i) + \delta(q_{j+1}^i, p_{j+1}^i)$. Since $\delta(p_{j-1}^i, q_{j+1}^i) > \sigma(w)$ (by inductive hypothesis), $\delta(p_{j-1}^i, p_j^i) \leq \sigma(x)$, $\delta(p_{j+1}^i, q_{j+1}^i) > \sigma(s)$, and $\delta(q_{j+1}^i, p_{j+1}^i) + \delta(p_{j+1}^i, p_{j+1}^i) > \sigma(s)$ +
Proposition 3. Let \( B \) be proofs of Section 4. \( \langle \text{interval for every \( tile \) \( \rangle \rangle \). By the definition of \( f \) \( \text{witness}. \) We use the following notations: \( TR \( F \rangle \) \( \langle \text{interval} \rangle \rangle \text{ TR} \). For a \( L \) \( \text{is a pLIS} \) \( \text{and we show that} \( \langle \text{A}_x \rangle \rangle \langle \text{tile} \rangle \rangle \langle \text{A}_x \rangle \rangle \text{tile} \rangle \rangle \text{due to the presence of the extra tile-interval,} \langle \text{p}^{i+1}_{n} \rangle \langle \text{p}^{i+1}_{n+1} \rangle \). \( \square \)

B Proofs of Section 4

Proposition 3. Let \( L \) be a pLIS_\( \varphi \) and \( d \in \mathbb{D}_L \). The following properties hold, unless \( \text{REQ}^L(d) \) is inconsistent:

- if \( \mathbb{D}^{<d} \neq \emptyset \), then \( f\text{-REQ}^L(d) = \mathcal{L}_L(d', d) \cap TR_f(\varphi) \), for any given \( d' \in \mathbb{D}^{<d} \), unless \( f\text{-REQ}^L(d) \) is inconsistent;

- if \( \mathbb{D}^{>d} \neq \emptyset \), then \( p\text{-REQ}^L(d) = \mathcal{L}_L(d, d') \cap TR_p(\varphi) \), for any given \( d' \in \mathbb{D}^{>d} \), unless \( p\text{-REQ}^L(d) \) is inconsistent.

Proof. We only prove the first part of the claim (the second one can be proved similarly). By the definition of \( f\text{-REQ}^L(d) \), it clearly holds \( f\text{-REQ}^L(d) \supseteq (\mathcal{L}_L(d', d) \cap TR_f(\varphi)) \) for any given \( d' \in \mathbb{D}^{<d} \). Let us assume that \( f\text{-REQ}^L(d) \) is consistent and let us suppose, towards a contradiction, that \( f\text{-REQ}^L(d) \not\supseteq (\mathcal{L}_L(d', d) \cap TR_f(\varphi)) \) for some \( d' \in \mathbb{D}^{<d} \). Thus, there is \( d'' \in \mathbb{D}^{<d} \) and a formula \( \psi \) such that \( \psi \in \mathcal{L}_L(d'', d) \cap TR_f(\varphi) \not\subseteq \mathcal{L}_L(d', d) \cap TR_f(\varphi) \), which means \( \psi \in \mathcal{L}_L(d'', d) \setminus \mathcal{L}_L(d', d) \). By the definition of \( \varphi\)-atom, we have that \( \text{neg} (\psi) \in \mathcal{L}_L(d', d) \), as \( \psi \not\in \mathcal{L}_L(d', d) \) and therefore, by the definition of \( f\text{-REQ}^L(d) \), we have that both \( \psi \) and \( \text{neg} (\psi) \) belong to \( f\text{-REQ}^L(d) \), contradicting the consistency hypothesis for \( f\text{-REQ}^L(d) \). \( \square \)

Lemma 9. An infinite \( \exists \forall -\text{pLIS}_\varphi \langle \mathbb{D}, L, \delta, X, Y \rangle \) exists if and only if a \( \varphi\)-witness \( L' = \langle \mathbb{D}', L', \delta', X', Y' \rangle \) exists.

Proof. For a \( \text{pLIS}_\varphi L = \langle \mathbb{D}, L, \delta, X, Y \rangle \) and \( \mathbb{D} \subseteq \mathbb{D}_L \), we denote by \( L|_{\mathbb{D}'} \) the \( \text{pLIS}_\varphi \langle \mathbb{D}, L, \delta, X, Y \rangle \), where \( X' = X, Y' = Y, \) and \( \delta \) and \( \bar{L} \) are the projection of, respectively, \( \delta \) and \( L \) to the elements of \( \mathbb{D} \).

(only-if direction) We identify a domain \( \mathbb{D}' \subseteq \mathbb{D} \) and we show that \( L|_{\mathbb{D}'} \) is a \( \varphi\)-witness. We use the following notations:
\[ L = \{ R \in \text{REQ}_{\text{L}} : \exists d \in D. (\text{REQ}^L_{\text{L}}(d) = R \text{ and } \forall d' \in D < d. \text{REQ}^L_{\text{L}}(d) \neq R) \} \]
\[ R = \{ R \in \text{REQ}_{\text{R}} : \exists d \in D. (\text{REQ}^R_{\text{R}}(d) = R \text{ and } \forall d' \in D > d. \text{REQ}^R_{\text{R}}(d) \neq R) \} \]
\[ U^L = \text{request-sets}^L(D) \setminus B^L \]
\[ U^R = \text{request-sets}^R(D) \setminus B^R \]

Intuitively, \( B^L \) (resp., \( B^R \)) is the set of left-bounded (resp., right-bounded) requests, that is, requests that have a leftmost (resp., rightmost) occurrence in \( L \); \( U^L \) (resp., \( U^R \)) is the set of left-unbounded (resp., right-unbounded) requests, that is, requests that do not have a leftmost (resp., rightmost) occurrence in \( L \).

We obtain \( D' \) through the following steps.

1. Let \( \hat{d}_{\min} \) be the smallest point in \( D \) such that \( \text{REQ}^L(d_{\min}) \in B^L \) (if \( B^L = \emptyset \), then let \( \hat{d}_{\min} \) be a randomly-chosen point in \( D \)) and let \( \hat{d}_{\max} \) be the greatest point in \( D \) such that \( \text{REQ}^L(d_{\max}) \in B^R \) (if \( B^R = \emptyset \) or \( \hat{d}_{\max} < \hat{d}_{\min} \), then let \( \hat{d}_{\max} = \hat{d}_{\min} \)).
2. Let \( d_1', d_2', d_3', d_4' \) be the greatest points in \( D \) such that (i) \( d_1' < d_2' < d_3' < d_4' \), (ii) \( \delta(d_{\min}, d_1') > \chi \), and (iii) \( \text{request-sets}^L(D[d_1', d_2']) = \text{request-sets}^L(D[d_1', d_3']) = \text{request-sets}^L(D[d_1', d_4']) \)
3. Let \( d_2', d_3', d_4', d_5', d_6', d_7', d_8', d_9', d_{10}' \) be the smallest points in \( D \) such that (i) \( \hat{d}_{\max} < d_2' < d_3' < d_4' \), (ii) \( \delta(d_{\max}, d_2') > \chi \), and (iii) \( \text{request-sets}^L(D[d_2', d_3']) = \text{request-sets}^L(D[d_2', d_4']) \)
4. For every \( d \in D[d_2', d_3'] \), pick a set \( E_d \in \mathcal{E}^L_{\text{L}}(d) \) and let \( E = \bigcup_{d \in D[d_2', d_3']} E_d \). Let \( d_{\min} = \text{pred}_{D}(\min(E \cup \{d_{11}', d_{12}'\})) \) and \( d_{\max} = \text{succ}_{D}(\max(E \cup \{d_{11}', d_{12}'\})) \).
5. Let \( D' = \{ d \in D' : \hat{d}_{\min} \leq d \leq \hat{d}_{\max} \} \).

We now prove that \( L|_{D'} \) is a \( \varphi \)-witness, \( E = D' < \hat{d}_{\min} \) and \( F = D' > \hat{d}_{\max} \) being, respectively, a left- and a right-period for it. Note that \( E \cap F = \emptyset \) and \( D' \setminus (E \cup F) \neq \emptyset \).

First, we observe that, due to Proposition \( \text{Proposition 2} \) and to the fact that \( L \) is fulfilling, sets of requests are preserved from \( L \) to \( L|_{D'} \). Formally, it holds \( \text{REQ}^L_{\text{L}}(d) = \text{REQ}^L_{\text{L}}(d) \) for every \( d \in D' \setminus \{d_{\min}, d_{\max}\} \), as well as \( p\text{-REQ}^L_{\text{L}}(d_{\min}) = p\text{-REQ}^L_{\text{L}}(d_{\min}) \) and \( f\text{-REQ}^L_{\text{L}}(d_{\max}) = f\text{-REQ}^L_{\text{L}}(d_{\max}) \). As an immediate consequence, since the labeling \( L' \) of \( L|_{D'} \) preserves the original one \( L \), universal requests are satisfied, that means that \( L|_{D'} \) is a \( \forall \text{-pLIS}_\varphi \). Moreover, due to step (4), \( D' \) contains a set of essentials of \( d \), for every \( d \in D' \setminus (E \cup F) \) (notice that \( D' \setminus (E \cup F) = D'[d_{\min}, d_{\max}] \subseteq D'[d_2', d_3'] \) and thus they are fulfilled in \( L|_{D'} \). What we are left to do is showing that \( E = \{ d \in D' : \hat{d}_{\min} \leq d < \hat{d}_{\min} \} \) and \( F = \{ d \in D' : \hat{d}_{\max} < d \leq \hat{d}_{\max} \} \) are, respectively, a left- and a right-period for \( L|_{D'} \). We only show that \( E \) is a left-period for \( L|_{D'} \); proving that \( F \) is a right-period for \( L|_{D'} \) can be done symmetrically. By the way it is defined, \( E \) is clearly a left-convex subset of \( D' \). Let us consider a point \( d \in E \) such that either \( d \) is not fulfilled in \( L|_{D'} \) or \( d = \min E \). In either case, \( d \in E < d' \) (this is trivially verified if \( d = \min E \); otherwise, it follows from the fact that points in \( D'[d_2', d_3'] \) are fulfilled in \( L|_{D'} \) (due to step (4)) and to the fact that \( L|_{D'} \) is a \( \forall \text{-pLIS}_\varphi \). It is not difficult to verify that \( E[d_3', d_{10}'] \) contains a point \( d' \) that is a representative of \( d \) in \( L|_{D'} \). Clearly, \( d < d' \) holds (as \( d \in E < d' \)). Moreover, condition \( \text{b} \) of Definition \( \text{Definition 2} \) is verified thanks to step (2), which forces all sets of requests occurring in \( E \) (except for the one associated with \( \min E \)) to occur both in \( E[d_3', d_{10}'] \) and in \( E[d_2', d_{10}'] \), as for the set of requests associated with \( \min E \), we have that \( f\text{-REQ}^L_{\text{L}}(\min E) = \emptyset \).
while $p\text{-REQ}^{L_{[d'')}}_{[d''],d'''}(\min E) = p\text{-REQ}^{L_{[d'')}}_{[d''],d'''}(\min E)$, and thus there exist $d'' \in \mathbb{E}^{d'',\min_d'}$, and $d''' \in \mathbb{E}^{d''\min_d'}$, with $p\text{-REQ}^{L_{[d'')}}_{[d''],d'''}(\min E) = p\text{-REQ}^{L_{[d'')}}_{[d''],d'''}(d''')$. Finally, condition (c) of Definition 2 is verified as well, for every $(A_x)_{\psi} \in f\text{-REQ}^{L_{[d']}}(d')$; thanks to step (2), we have $\delta(d',d_{\text{min}}) > \lambda'$; moreover, since $d'$ is fulfilled, there must be a point $d'' \in \mathbb{D}^{d'}$ such that $(A_x)_{\psi}$ is fulfilled in $(L, d')$ by $d''$, with $\delta(d',d'') \leq \lambda'$, hence it clearly holds $d'' < d_{\text{min}},$ which implies $d'' \in \mathbb{E}$.

(if direction) Let $E$ and $F$ be, respectively, a left- and a right-period for $L'$ and let $\hat{\mathbb{D}} = \mathbb{D}' \setminus (E \cup F)$. Intuitively, we first obtain the domain $\mathbb{D}$ of $L$ from the domain $\mathbb{D}'$ of $L'$ by iterating the two periods $E$ and $F$, and then we define $\delta$ and $L$ as suitable extensions of, respectively, $\delta'$ and $L'$ to the new, extended domain $\hat{\mathbb{D}}$. Intuitively, $L$ is defined so that the set of requests of a point in $L$ is the same as the set of requests of the corresponding point in $L'$. This is possible thanks to the next observation, which follows from Proposition 3:

it is possible, for every $d \in \mathbb{D}$, to force $f\text{-REQ}^{L_{[d']}}(d)$ to be equal to $f\text{-REQ}^{L_{[d']}}(\hat{d})$, for some given $\hat{d} \in \mathbb{D}'$ (except for $\hat{d} = \min \mathbb{D}'$), by setting, for every $d' \in \mathbb{D}^{d'}$, $L(d',d) = L'(d'',\hat{d})$ for some $d''$; similarly, it is possible to force $p\text{-REQ}^{L'}_{[d]}(d)$ to be equal to $p\text{-REQ}^{L'}_{[d]}(\hat{d})$, for some given $\hat{d} \in \mathbb{D}'$ (except for $\hat{d} = \max \mathbb{D}'$).

Notice also that we are guaranteed of the consistency of $f\text{-REQ}^{L'}_{[d]}(\hat{d})$ and $p\text{-REQ}^{L'}_{[d]}(\hat{d})$, required to apply Proposition 3, because every point in $\mathbb{D}'$ is either fulfilled or a point with the same set of requests is fulfilled in $L'$ (by the definition of $\varphi$-witness).

Formally, we define $\mathbb{D}$ as $(E \times \mathbb{Z}^{<0}) \cup ((\hat{\mathbb{D}} \times \{0\}) \cup (F \times \mathbb{N}^{>0}))$, the underlying ordering relation $\prec_{\mathbb{D}}$ being defined as (in the reminder of the proof we use $\prec_{\mathbb{D}'}$ to denote the ordering relation over $\mathbb{D}'$ and $\prec_\mathbb{D}$ to denote the one over $\mathbb{D}$, while the symbol $\prec$ is used to denote the standard ordering relation over $\mathbb{Z}$): for every $(d,k), (d',k') \in \mathbb{D}$ (i) if $k < k'$, then $(d,k) \prec_{\mathbb{D}} (d',k')$, and (ii) if $k = k'$, then $(d,k) \prec_{\mathbb{D}} (d',k')$ if and only if $d \prec_{\mathbb{D}'} d'$. The metric $\delta$ is defined as follows:

- for every $(d,k), (d',k') \in \mathbb{D}$, with $k = k'$, we set $\delta(d',d'') = \delta'(d',d'')$;
- $\delta((\max \mathbb{E},k),(\min \mathbb{E},k+1)) = \delta((\max \mathbb{E},-1),(\min \hat{\mathbb{D}},0)) = \delta'(\max \mathbb{E},\min \hat{\mathbb{D}})$ for every $k \in \mathbb{Z}^{<1}$;
- $\delta((\max \mathbb{F},k),(\min \mathbb{F},k+1)) = \delta((\max \hat{\mathbb{D}},0),(\min \mathbb{F},1)) = \delta'(\max \hat{\mathbb{D}},\min \mathbb{F})$ for every $k \in \mathbb{N}^{>0}$.

The above definition leaves $\delta$ undefined for some $(d',d'') \in \mathbb{D} \times \mathbb{D}$. However, the value of $\delta$ over those inputs follows from the properties of the metric space we consider; in particular, it always holds $\delta(d',d'') = \delta(d',d'') = \delta(d',d'') + \delta(d',d'')$ for every $d''$, with $d' \leq d'' \leq d'''$.

In what follows, slightly abusing the notation, we sometimes identify $(d,k)$ simply with $d$, for $(d,k) \in \mathbb{D}$ with $k \in \{0, 1\}$. Moreover, for every $d \in \mathbb{D}'$ that is fulfilled in $L'$, we pick from $\hat{E}_{L'}(d)$ a set of essentials of $d$, and we denote it by $E_d$. We define the labeling function $L$ as follows.

A. For every $d \in \hat{\mathbb{D}}$ (thus $d$ is fulfilled in $L'$, by the definition of $\varphi$-witness) and every $d' \in E_d$, we set:

- $L([d',d]) = L'([d',d])$, if $d' \prec_{\mathbb{D}'} d$;
- $L([d,d']) = L'([d,d'])$, if $d \prec_{\mathbb{D}'} d'$.
B. For every $d \in \mathbb{E}$, we proceed as follows.
- If $d$ is fulfilled in $L'$ and $d \neq \min \mathbb{E}$, then, for every $d' \in E_d$ and every $k \in \mathbb{Z}^{<0}$, we set:
  - $L((d', k), (d, k)) = L'(d', d)$, if $d' \prec_{L'} d$;
  - $L((d', k), (d', k)) = L'(d', d')$, if $d \prec_{L'} d'$ and $d' \in \mathbb{E}$;
  - $L((d, k), d') = L'([d, d'])$, if $d \prec_{L'} d'$ and $d' \in \mathbb{D} \cup \mathbb{F}$.
- If $d$ is not fulfilled in $L'$ or $d = \min \mathbb{E}$, then let $r$ be the representative of $d$ in $L'$ fulfilling conditions of Definition 2. For every $d' \in E_r$ and every $k \in \mathbb{Z}^{<0}$, we set:
  - $L((d', k - 1), (d, k)) = L'(d', r)$, if $d' \prec_{L'} r$;
  - $L((d, k), (d', k)) = L'([r, d'])$, if $r \prec_{L'} d'$ and $d' \in \mathbb{E}$;
  - $L((d, k), d') = L'([r, d'])$ if $r \prec_{L'} d'$ and $d' \in \mathbb{D} \cup \mathbb{F}$.

C. For every $d \in \mathbb{F}$, we proceed analogously to item B.

It is important to notice that labels set in the second sub-case of step B do not conflict with (i.e., do not overwrite) any of the labels set in the previous steps. Clearly there is not conflict between labels set in the first sub-case of step B and labels set in the second one. Suppose, towards a contradiction, that there is an interval $[(d, k), (d', 0)] \in \mathbb{I}(\mathbb{D})$ whose label is set in step A (because $d' \in \mathbb{D}$ and $d \in E_{d'}$) and then overwritten in the second sub-case of step B (because $d \in \mathbb{E}$ is such that either $d$ is not fulfilled in $L'$ or $d = \min \mathbb{E}$, $d' \in E_r$, and $r$ is a representative of $d$ in $L'$ fulfilling conditions of Definition 2). By the properties of $r$ (Definition 1), we know that $d'$ is fulfilled in $L'$ and so are points in $E_{d'}$, as well as that $\min \mathbb{E} \notin E_{d'}$. Since $d \in E_{d'}$ (by the conditions for step A), we have that $d$ is fulfilled in $L'$ and $d \neq \min \mathbb{E}$, which contradicts the conditions for the second sub-case of step B.

The definition of $L$ we provided so far is incomplete, but it is possible to verify that, by setting $X = 2 \cdot |\mathbb{D}'|$ (and $Y = |Y|$), all existential requests are fulfilled in $L$, for every point in $\mathbb{D}$. In order to complete the labeling it is enough, for every interval $[d, d'] \in \mathbb{I}(\mathbb{D})$ for which $L((d, d'))$ is still undefined, to set $L((d, d')) = L'([d', d'])$ for some $d'', d''' \in \mathbb{D}'$ such that $\text{REQ}^L(d) = \text{REQ}^{L'}(d'')$ and $\text{REQ}^L(d') = \text{REQ}^{L'}(d')$. The resulting pLIS $L$ is a $3\text{-pLIS}_{\varphi}$.

It is important to notice that, thanks to Proposition 5 and the above observation [1] following from it, we have that $\text{REQ}^{L'}((d, k)) = \text{REQ}^{L'}(d')$ holds for every $d \in \mathbb{E}$ (except for $d = \min \mathbb{E}$, for which we have $\text{p-REQ}^{L'}((\min \mathbb{E}, k)) = \text{p-REQ}^{L'}(\min \mathbb{E})$). This is crucial for the fulfillment of existential requests.

Additionally, since $L'$ is a $\forall$-pLIS $\varphi$ (by Definition 3), so is $L$. The thesis follows.

\[ \square \]

**Lemma 10.** Let $L = \langle \mathbb{D}, \mathbb{L}, \delta, X, Y \rangle$ be a $\varphi$-witness, $\mathbb{E}$ and $\mathbb{F}$ being, respectively, a left- and a right-period for it. If $|\mathbb{E}| > B_\varphi$ (resp., $|\mathbb{F}| > B_\varphi$, $|\mathbb{D} \setminus (\mathbb{E} \cup \mathbb{F})| > B_\varphi$), then there is a $\varphi$-witness $L' = \langle \mathbb{D}', \mathbb{L}', \delta', X', Y' \rangle$ with $|\mathbb{D}'| = |\mathbb{D}| - 1$.

**Proof.** We prove the claim under the assumption that $|\mathbb{E}| > B_\varphi$. The other cases ($|\mathbb{F}| > B_\varphi$ and $|\mathbb{D} \setminus (\mathbb{E} \cup \mathbb{F})| > B_\varphi$) can be proven analogously and the proof is omitted.
For every $d \in \mathbb{E}$, we put $\text{repr}(d) = \max(\{d' \in \mathbb{E} \mid d' \text{ is a representative of } d \text{ in } \mathbf{L}\})$ ($\text{repr}(d)$ is the canonical representative of $d$ in $\mathbf{L}$). By Definition 1 for every $d, d' \in \mathbb{E}$ if $\text{REQ}^{\mathbf{L}}(d) = \text{REQ}^{\mathbf{L}}(d')$, then $\text{repr}(d) = \text{repr}(d')$. Thus $\text{REPR} = \{\text{repr}(d) \mid d \in \mathbb{E}\}$ is such that $|\text{REPR}| \leq |\text{REQ}|$. Moreover, we fix, for every $r \in \text{REPR}$, a set $E_r^2 \in E^2_r(r)$ of 2nd-order essentials of $r$ in $\mathbf{L}$. Clearly, $|E_r^2| \leq |\text{TR}(\varphi)| \leq |\mathcal{C}(\varphi)|$ and $|\bigcup_{r \in \text{REPR}} E_r^2| \leq |\text{REQ}| \cdot |\mathcal{C}(\varphi)|$.

Since $|\mathbb{E}| > B_2$, there are $R \in \text{REQ}$ and at least $(2 \cdot |\mathcal{C}(\varphi)|^2 + 2 \cdot |\mathcal{C}(\varphi)| + 1)$ points $d \in \mathbb{E}$ such that $\text{REQ}^L(d) = R$, $d \notin \text{REPR}$, and $d \notin \bigcup_{r \in \text{REPR}} E_r^2$. We collect such points in the set $\text{REMOVAL}$ and we denote by $\text{REMOVAL}^{>d}$ (resp., $\text{REMOVAL}^{<d}$) the set $\{d' \in \text{REMOVAL} \mid d' > d\}$ (resp., $\{d' \in \text{REMOVAL} \mid d' < d\}$), for every $d \in \mathbb{D}$.

Let $d_e \in \text{REMOVAL}$ be a point such that there are at least $(|\mathcal{C}(\varphi)|^2 + |\mathcal{C}(\varphi)|)$ points in $\text{REMOVAL}^{<d_e}$ and at least $(|\mathcal{C}(\varphi)|^2 + |\mathcal{C}(\varphi)|)$ points in $\text{REMOVAL}^{>d_e}$. We show how to build the desired $\varphi$-witness $\mathbf{L}'$, where $\mathcal{D}' = \mathbb{D} \setminus \{d_e\}$, $\delta'$ is the projection of $\delta$ to $\mathbb{D}'$, $\mathcal{X}' = [\mathbb{D}]'$, and $\mathcal{Y}' = \mathcal{Y}$. As for $\mathcal{L}$, it is not possible to simply define it as the projection of $\mathcal{L}$ to $\mathcal{D}'$ because the removal of $d_e$ might generate defects, such as the presence of a point $d \in \mathbb{D}^{<d_e}$ (resp., $d \in \mathbb{D}^{>d_e}$) for which there is $\psi \in \text{f-REQ}^{\mathbf{L}}(d)$ (resp., $\psi \in \text{p-REQ}^{\mathbf{L}}(d)$) such that $d_e$ is the only point in $\mathbb{D}^{>d}$ (resp., $\mathbb{D}^{<d}$) that fulfills $\psi$ in $\mathbf{L}'$.

In order to prevent such defects, our definition of $\mathcal{L}'$ guarantees that points that are fulfilled in $\mathbf{L}$ are fulfilled in $\mathbf{L}'$, too. Formally, we define $\mathcal{L}'$ as follow. Consider a point $d \in \mathbb{D} \setminus \{d_e\}$, with $d < d_e$ (the case with $d > d_e$ can be dealt with analogously), that is fulfilled in $\mathbf{L}$, and assume that for some $\psi \in \text{f-REQ}^{\mathbf{L}}(d)$ there is no point $d' \in \mathbb{D}^{>d_e}$ for which $\psi$ is fulfilled in $\mathbf{L}$ by $d'$. We use a point $e \in \text{REMOVAL}^{>d_e}$ to fix such a defect. In order to properly choose such a point $e$ we proceed as follows.

Let $P_{d_e} = E_{d_e} \cap \mathbb{D}^{<d_e}$ (past essentials of $d_e$ in $\mathbf{L}$) and, for all $d_e \in P_{d_e}$, let $F_{d_e} = E_{d_e} \cap \mathbb{D}^{>d_e}$ (future 2nd-order essentials of $d_e$ in $\mathbf{L}$). Clearly, $|\bigcup_{d_e \in P_{d_e}} F_{d_e}| \leq |\mathcal{C}(\varphi)|^2$.

Now, let $F_d = E_d \cap \mathbb{D}^{>d}$ (future essentials of $d$ in $\mathbf{L}$). We have that $d_e \in F_d$ and $|F_d \setminus \{d_e\}| < |\mathcal{C}(\varphi)|$ (as $|F_d| \leq |\mathcal{C}(\varphi)|$). Thus, there exists a point $e \in \text{REMOVAL}^{>d_e}$ such that $e \notin \bigcup_{d_e \in P_{d_e}} F_{d_e}$ and $e \notin F_d$; in order to fix the potential defect caused by the removal of $d_e$, we make $e$ play its role: we set $\mathcal{L}'([d, e]) = \mathcal{L}([d, d_e])$ and $\mathcal{L}'([d', e]) = \mathcal{L}([d', d_e])$ for every $d' \in P_{d_e}$. Since $\text{REQ}^L(d_e) = \text{REQ}^L(e)$ and due to the properties of $e$ (in particular, it is unessential to the fulfillment of any of the points in $P_{d_e} \cup \{d_e\}$), the new labeling does not introduce any new defect, while preventing the aforementioned one ($\psi$ is fulfilled in $\mathbf{L}'$ by $e$). Other potential defect, involving other requests $\psi' \in \text{REQ}^L(d)$ or other points $f \in \mathbb{D}$, can be dealt with using the same argument, thus obtaining the pLIS $\mathbf{L}'$ enjoying the property: for every $d \in \mathbb{D} \setminus \{d_e\}$, if $d$ is fulfilled in $\mathbf{L}$, then it is fulfilled in $\mathbf{L}'$, too.

In order to verify that $\mathbf{L}'$ is actually a $\varphi$-witness, it suffices to observe that the new labeling does not involve any of the points in $\text{REPR}$ or $\bigcup_{r \in \text{REPR}} E_r^2$, which means that, for every $d \in \mathbb{E} \setminus \{d_e\}$, if $\text{repr}(d) \in \text{REPR}$ is a representative of $d$ in $\mathbf{L}$, then it is a representative of $d$ in $\mathbf{L}'$ as well. The thesis follows. □