

NWin: A Tool for Counting Winning Strategies

Vadim Malvone
Università degli Studi di Napoli
Federico II, Italy
vadim.malvone@unina.it

Aniello Murano
Università degli Studi di Napoli
Federico II, Italy
murano@na.infn.it

Marco Tafuto
Università degli Studi di Napoli
Federico II, Italy
marc.tafuto@gmail.com

ABSTRACT

We present NWin, a tool that allows to count all different winning strategies in two-player turn-based games under the reachability condition. NWin uses a graphical interface to build the game model and collect all acyclic and cyclic winning strategies. By means of benchmarks over random games we show that NWin has a good performance in practice.

Categories and Subject Descriptors

I.2.11 [Artificial Intelligence]: Distributed Artificial Intelligence — *Multiagent Systems*

General Terms

Algorithms, Performance

Keywords

Game theory; Reachability condition; Strategic reasoning

1. INTRODUCTION

Game theory is a powerful framework with several applications in MAS [14]. It allows reasoning efficiently about the strategic behavior of reactive systems [2, 9, 13]. In this paper we consider two-players turn-based games played under the *reachability* condition, i.e., some nodes are declared *target*. Solving such a game amounts to check whether one of the players has a *winning strategy*, i.e., a sequence of moves that lead him to a target node no matter how the opponent acts.

In many cases, knowing how many winning solutions exist is crucial [4, 6–8, 10, 11]. For example, in planning a rescue, it would give to a rescuer some backup plan in case something goes wrong. In solution concepts, this would cope with the *uniqueness* problem in Nash equilibrium (see [1, 5, 12]).

In this paper we introduce NWin, a tool that addresses the quantitative question of checking how many different strategies a player has to win a two-player reachability game. The tool uses a graphical interface to build the game model and shows all acyclic and cyclic winning strategies. By means of benchmarks over random games we show that NWin has a good performance in practice: it can process 10^8 acyclic strategies in less than 10 seconds by a pc.

Appears in: *Proceedings of the 15th International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2016)*, J. Thangarajah, K. Tuyls, C. Jonker, S. Marsella (eds.), May 9–13, 2016, Singapore.

Copyright © 2016, International Foundation for Autonomous Agents and Multiagent Systems (www.ifaamas.org). All rights reserved.

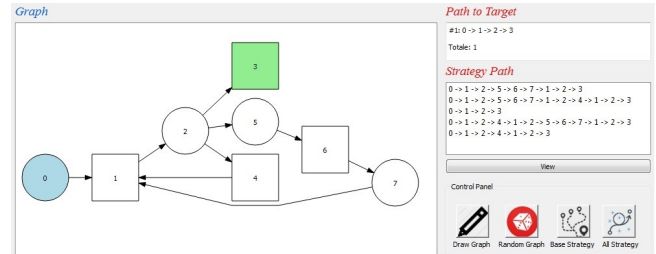


Figure 1: The main window of NWin.

2. THE TOOL

In this section we describe the Graphical User Interface (GUI) of NWin, in the current release (1.0).

Our tool works over two-player turn-based games, played by Player 1 and Player 2, under the reachability condition (2TG, for short). These are directed graphs in which the set of nodes (V) is partitioned in two subsets V_1 and V_2 . Each V_i contains all nodes owned by Player i . Nodes in V_1 (V_2) are graphically represented by a circle (square). The unique initial node is colored in blue and all target nodes (T) in green. Take a node v , the set of outgoing edges represent all possible moves of the player that owns v . A play is a path starting from the initial node and represents a sequence of performed moves from the players. A strategy for a player is the set of moves he can perform along every prefix of a play. A strategy is *winning* for Player 1 if it induces a play that reaches a target node, no matter which strategy Player 2 uses.

The GUI is depicted in Figure 1. It consists of two parts: the Output Areas (OA) and the Control Panel (CP). The OA is made of three frames. The one on the left side (*Graph*) is used to depict the game graph. The frame on the right upper side (*Path to Target*) shows all *reachable paths* that start at the initial node and end in a target node¹. Finally, the frame of right lower side (*Strategy Path*) reports all winning strategy plays for Player 1. The CP at the right down corner is composed by four buttons: Draw Graph (DG), Random Graph (RG), Base Strategies (BS), and All Strategies (AS). The DG button is used to build a graph manually. By pressing it, a window pops up in which the user sets the number of nodes and edges of the game graph. Then, another window comes out in which the user decides how the nodes are connected. Finally, he sets in a new window the initial

¹Formally, these are the reachability paths obtained by looking at the monolithic version of the game graph.

and the set of target nodes. The RG button works similarly to the DG button but after the parameters in the first window are set the game is generated randomly. The BS button works as follows. The first time it is pressed, all reachable paths are shown. At the second press it gives all possible acyclic winning strategy plays in which the Player 1 wins. The AS button works as the BS button, but it also reports the cyclic plays. Finally, if we select a winning strategy play in the frame *Strategy Path* and push the button View (V), in the game graph the path appears in red.

A video demonstration of NWin is on YouTube ².

3. HOW TO COMPUTE THE STRATEGIES

Given a *2TG*, NWin computes all winning strategies through three main steps. The first two are preliminary and used to partition all nodes in “good” and “bad”.

The first step calculates all acyclic reachability paths, *i.e.* the acyclic paths, from the initial node to a target node, that are present in the monolithic version of the game graph. This is done by applying a classic DFS algorithm. Precisely, the algorithm uses two sets of nodes, namely *white* (W) and *black* (B). The set W (B) represents all nodes that can (cannot) reach a target node in T . This step starts with $B = \emptyset$ and $W = T$. For each node v , if it is adjacent to a node in W , then $W = W \cup \{v\}$, otherwise $B = B \cup \{v\}$. The algorithm ends when a fixed point is reached.

The second step works on the nodes in $\{W \cap V_2\} \setminus T$, *i.e.* the nodes of Player 2 that are white but not target nodes. Along this step we remove a node v from W and add it in B iff at least one of the following conditions is satisfied: (i) v has a loop; (ii) v is adjacent to a node in B ; (iii) v belongs to a *trap* cycle C for Player 1 (from which he can not go out). Note that, each $v' \in C \cap V_1$ has a single outcome edge.

The third step considers the entire game and in particular the strategies of the players. Given a node $v \in W \cap V_1 \setminus T$, Player 1 has a degree of preference in the mining that, if there exists a node v' adjacent to v and $v' \in W$, then he chooses and moves to v' (even if this node has been already visited). Similarly, given a node $v \in W \cap V_2$, if there exists a node v' adjacent to v and $v' \in B$, then Player 2 chooses v' , otherwise he prefers to choose a node that has been already visited, if possible. This step, and thus the algorithm, ends when a target node or a node in B is entered.

It is important to note that, after the first step the tool prints all possible reachability paths. All winning strategy plays are printed only after the third step is completed.

4. CRITICAL ISSUE

To compute all winning strategy plays, we have faced with two main critical issues: all the edges need to be visited in order to discover cycles and nodes require to be visited more than ones whenever they belong to a winning strategy play. The classical DFS is too weak to handle these two points. Indeed, the DFS analyzes all the nodes of the graph, but it does not analyze all edges and so all possible moves of both players. For this reason, we have introduced opportune extensions of the DFS. The first we consider is DFSR, in which it allows the algorithm to *revisit* a node in order to consider all possible edges and all possible acyclic winning strategy plays. In order to retrieve the winning strategy plays for Player 1 that contain also cycles, we have built MDFSR

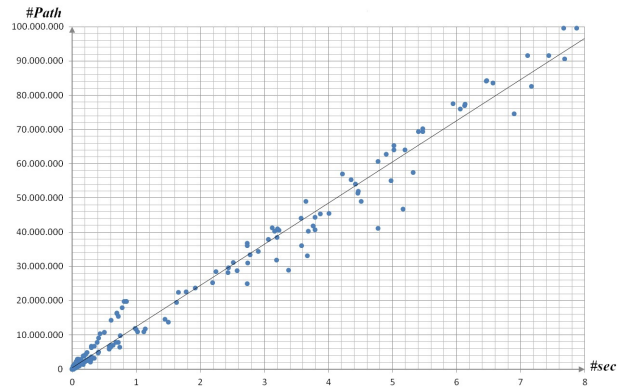


Figure 2: The table of performance.

a modified version of the DFSR that is able to collect plays in which there are cycles repeated at most once. We consider only this kind of cycles for two reasons: (i) one can pump a cycle an arbitrary number of times to obtain other winning plays, (ii) to avoid the algorithm running forever. As last remark it is worth noting that the DFSR is used to visit several times the same node while the MDFSR version is required to visit more than ones the same edge.

5. PERFORMANCE

In this section we report on some benchmarks. For the lack of space we only describe those over DSFR. We have run NWin on an i5 processor with 4GB of RAM. We have considered random games evaluated under the RG button by setting as number of nodes $n \in \{2, \dots, 16\}$ and number of edge $e \in \{n + 1, \dots, n^2\}$. In particular, we have executed one hundred cases for each n and thus one thousand and five hundred games in total. For each game, we have collected the execution time and the number of paths processed.

The benchmarks are depicted in Figure 2 in which we report the number of paths ($\#Path$) processed per second (s). The graph gives a proportional relationship between the number of paths processed and the seconds that NWin takes to process such paths. In particular, it shows that under 10 seconds NWin can process more than 10^8 paths. It is worth observing that we analyze the number of paths rather than nodes as the former is the fulcrum of NWin.

6. CONCLUSION

In this paper, we have presented NWin a tool that allows to retrieve all possible winning strategy plays in a two-player game under the reachability condition. NWin makes use of a simple but efficient GUI that allows to build the game under two options: random and manual. The tool calculates and reports, upon request, all acyclic and cyclic winning strategy plays. We have reported on some benchmarks on the former case and showed that NWin can calculate more than 10^8 paths in less than 10 seconds. We believe that our tool can be used as a core engine to solve several problems in MAS. As future work we plan to extend this tool in the setting of solution concepts, *e.g.* Nash Equilibrium (NE). In particular, by means of this extension, we aim to solve the uniqueness of NE in practice [3].

² www.youtube.com/playlist?list=PL0f6qAJrAYnFB15PXUbloDMGyj1kif9aF

REFERENCES

- [1] E. Altman, H. Kameda, and Y. Hosokawa. Nash equilibria in load balancing in distributed computer systems. *IGTR*, 4(2):91–100, 2002.
- [2] R. Alur, T. Henzinger, and O. Kupferman. Alternating-Time Temporal Logic. *JACM*, 49(5):672–713, 2002.
- [3] B. Aminof, V. Malvone, A. Murano, and S. Rubin. Graded Strategy Logic: Reasoning about Uniqueness of Nash Equilibria. In *AAMAS'16*. International Foundation for Autonomous Agents and Multiagent Systems, 2016, (to appear).
- [4] P. Bonatti, C. Lutz, A. Murano, and M. Vardi. The Complexity of Enriched muCalculi. *LMCS*, 4(3):1–27, 2008.
- [5] R. Cornes, R. Hartley, and T. Sandler. An elementary proof via contraction. *Journal of Public Economic Theory*, 1(4):499–509, 1999.
- [6] M. Faella, M. Napoli, and M. Parente. Graded Alternating-Time Temporal Logic. *FI*, 105(1-2):189–210, 2010.
- [7] A. Ferrante, A. Murano, and M. Parente. Enriched Mu-Calculi Module Checking. *LMCS*, 4(3):1–21, 2008.
- [8] O. Kupferman, U. Sattler, and M. Vardi. The Complexity of the Graded muCalculus. In *CADE'02*, LNCS 2392, pages 423–437. Springer, 2002.
- [9] O. Kupferman, M. Vardi, and P. Wolper. Module Checking. *IC*, 164(2):322–344, 2001.
- [10] V. Malvone, F. Mogavero, A. Murano, and L. Sorrentino. On the counting of strategies. In *TIME 2015*, pages 170–179, 2015.
- [11] V. Malvone, A. Murano, and L. Sorrentino. Games with additional winning strategies. In *CILC 2015*, pages 175–180, 2015.
- [12] G. Papavassilopoulos and J. B. Cruz. On the uniqueness of nash strategies for a class of analytic differential games. *Journal of Optimization Theory and Applications*, 27(2):309–314, 1979.
- [13] A. Pnueli and R. Rosner. Distributed reactive systems are hard to synthesize. In *FOCS'90*, pages 746–757. IEEE, 1990.
- [14] Y. Shoham and K. Leyton-Brown. *Multiagent Systems: Algorithmic, Game-Theoretic, and Logical Foundations*. Cambridge University Press, 2008.